# I-7005 and M-7005

# User's Manual

## Warranty

All products manufactured by ICP DAS are under warranty regarding defective materials for a period of one year from the date of delivery to the original purchaser.

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Date: 2006/09/22

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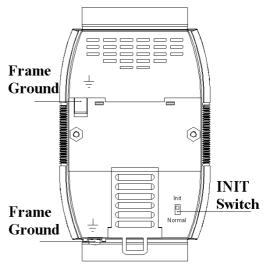
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# 1. Introduction

The I-7000 series is a family of network data acquisition and control modules, providing analog-to-digital, digitalto-analog, digital input/output, timer/counter and other functions. The modules can be remotely controlled using a set of commands, which we call the DCON protocol. Communication between the module and the host is in ASCII format via an RS-485 bi-directional serial bus standard. Baud Rates are software programmable and transmission speeds of up to 115.2 Kbps can be selected.

Some I-7000 modules feature a new design for the frame ground and INIT switch as shown in the figure (rear view). The frame ground provides enhanced static protection (ESD) abilities and ensures the module is more reliable. The INIT switch allows easier access to INIT mode. Please refer to Sections A.1 and A.3 for more details.



The common features of the I-7005 and M-7005 modules are as follows:

- 1. 24-bit sigma-delta ADC to provide excellent accuracy
- 2. Direct thermistor connection
- 3. Software calibration

The I-7005/M-7005 is an 8-channel thermistor input and 6-channel digital output module

Supported thermistor types are as follows:

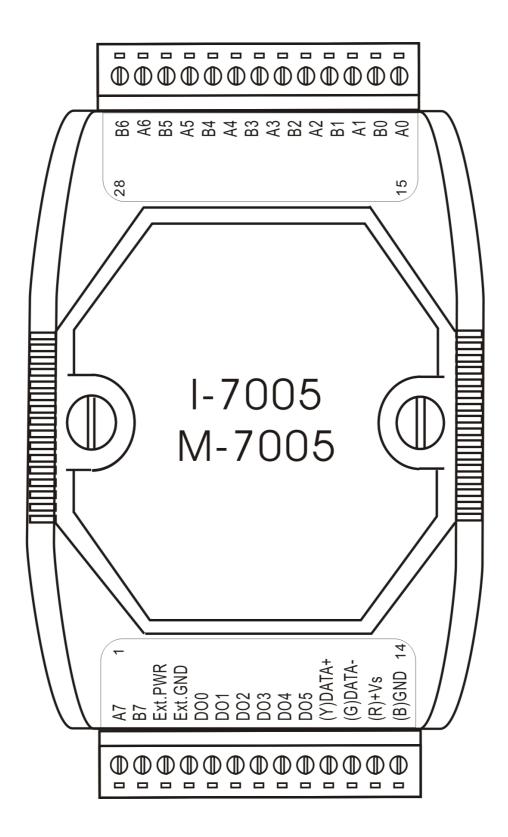
- 1. PreCon Type III, Model 3, 10,000 Ohms at 25°C (77°F)
- 2. Fenwell Type U, 2000 Ohms at 25°C
- 3. YSI L Mix, 100 Ohms at 25°C
- 4. YSI L Mix, 300 Ohms at 25°C
- 5. YSI L Mix, 1000 Ohms at 25°C
- 6. YSI B Mix, 2252 Ohms at 25°C
- 7. YSI B Mix, 3000 Ohms at 25°C
- 8. YSI B Mix, 5000 Ohms at 25°C
- 9. YSI B Mix, 6000 Ohms at 25°C
- 10. YSI B Mix, 10000 Ohms at 25°C
- 11. YSI H Mix, 10000 Ohms at 25°C
- 12. YSI H Mix, 30000 Ohms at 25°C
- 13.User-defined

## **1.1 More Information**

For more information regarding the I-7000 series, please refer to chapter 1 of the "I-7000 Bus Converter User's Manual" as shown below or visit the ICP DAS website <u>http://www.icpdas.com</u>.

- 1.1 The 7000 Series Overview
- 1.2 Related Documentation for the 7000 Series
- 1.3 Common Features of the 7000 Series
- 1.4 The 7000 Series System Network Configuration
- 1.5 7000 Dimensions

## **1.2 Terminal Assignment**



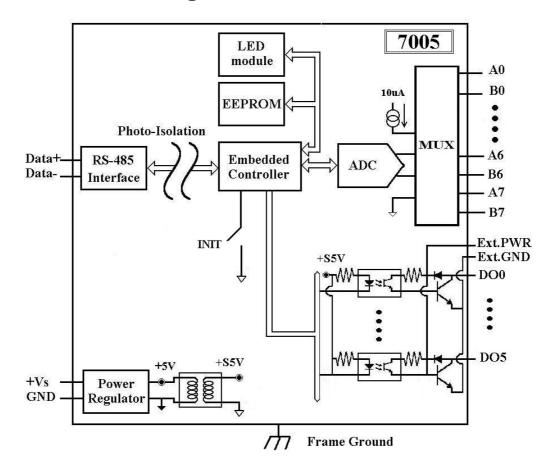
## **1.3 Specifications**

	I-7005/M-7005
Analog Input	
Input Channels	8
Input Type	Thermistor
Thermistor Type	PreCon Type III, Fenwell Type U,
	YSI L 100, YSI L 300, YSI L 1000,
	YSI B 2252, YSI B 3000,
	YSI B 5000, YSI B 6000, YSI B
	10000, YSI H 10000, YSI H 30000,
	User-defined
Temperature Scale	Celsius, Fahrenheit
Sampling Rate	8 samples/sec
Bandwidth	5.24 Hz
Accuracy	±0.1%
Zero Drift	0.5 μV/°C
Span Drift	20 μV/°C
CMR@50/60Hz	86 dB min
NMR@50/60Hz	100 dB min
Isolation	3000 VDC
Open Wire Detection	Yes
Individual Channel	Yes
Configurable	
Digital Output	
Output Channels	6
Output Type	Open collector
Output Load	30 V, 100 mA max.
Modbus RTU	M-7005
Power	
Requirement	+10 to +30 VDC
Consumption	1.1 W
Temperature Range	
Operating	-25°C to +75°C
Storage	-30°C to +75°C

**Note**: A warm up period of 30 minutes is recommended in order to achieve the complete performance results described in the specifications.

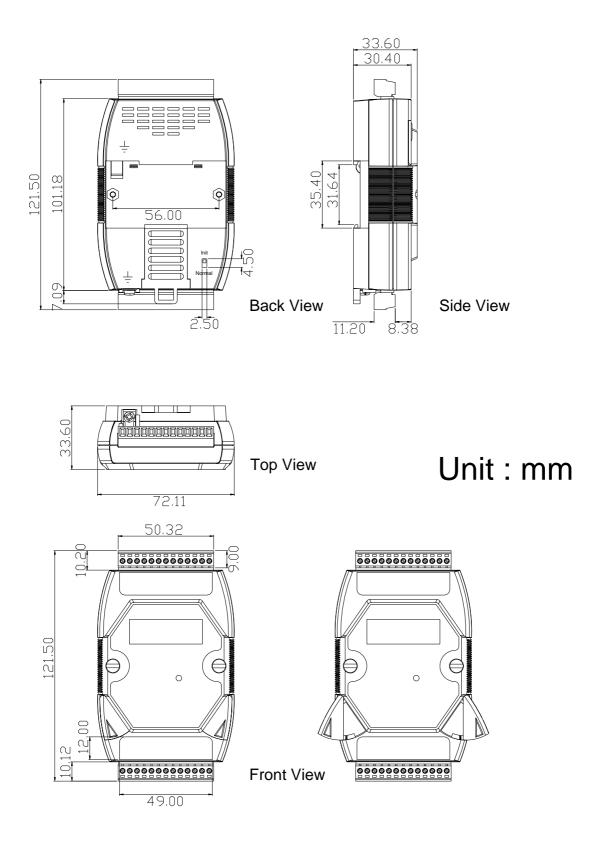
## **1.4 Block Diagrams**

#### 1.4.1 Block Diagram for the I-7005/M-7005



## **1.5 Dimensions**

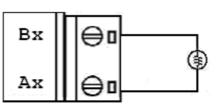
### 1.5.1 I-7005 and M-7005 Dimensions



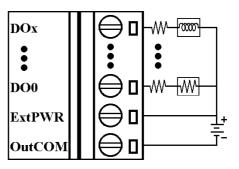
## 1.6 Wiring

## 1.6.1 I-7005/M-7005 Wiring

**Thermistor connection** 



**Digital output connectoin** 



## 1.6.2 Wiring Recommendations

- Use 26-12 AWG wire for signal connections.
- Strip the wire to a length of  $7\pm0.5$  mm.
- Use a crimp terminal for wiring.
- Avoid high-voltage cables and power equipment as much as possible.
- For RS-485 communication, use insulated and twisted pair 24 AWG wire, e.g. Belden 9841.

## **1.7 Quick Start**

To install the module, follow the steps below:

- 1. Connect the thermistor sensor. See Section 1.2 for the terminal assignment and Section 1.6 for the wiring diagram.
- 2. Connect the module to the RS-485 network using the DATA+ and DATA- terminals. See Section 1.2 for the terminal assignment. If the host is only equipped with an RS-232 interface, then an RS-232 to RS-485 converter will be required. Refer to the "I-7000 Bus Converter User's Manual" for more information.
- 3. Connect the module to the power supply using the +Vs and GND terminals. See Section 1.2 for the terminal assignment. Note that the voltage supplied to the module should be in the range of +10 to +30 VDC.
- 4. Configure the module by sending the %AANNTTCCFF command. See Section 2.1 for details. To configure the I-7005, the \$AA7CiRrr command must also be sent. See Section 2.12 for details. For M-7000 modules using the Modbus RTU protocol, configure the module using the following functions.
  - □ Sub-function 04h of Function 46h, see Section 3.6.2
  - □ Sub-function 06h of Function 46h, see Section 3.6.4
  - Sub-function 08h of Function 46h, see Section 3.6.6
     The default settings for the module can be found in Section 1.8.
- 5. For the I-7005, send the ~AADT command to set the temperature scaling. See Section 2.23 for details.
- To read data from the input channels, send either the #AA or #AAN commands to the module. See Sections 2.3 and 2.4 for details. For M-7000 modules using the Modbus RTU protocol, use Function 04h to read the

data from the input channels. See Section 3.3 for details.

7. If the host is a PC with a Windows operating system installed, the DCON Utility can be used to allow easy configuration and reading of data. The DCON Utility can be downloaded from the ICP DAS website (<u>http://www.icpdas.com</u>). The documentation for the DCON Utility can be found in the "**Getting Started For I-7000 Series Modules**" manual.

Please refer to the "I-7000 Bus Converter User's Manual" and "Getting Started For I-7000 Series Modules" manuals for more details. The "Getting Started For I-7000 Series Modules" manual can be downloaded from the ICP DAS website (http://www.icpdas.com).

## **1.8 Default Settings**

Default settings for the I-7005 are as follows:

- Module Address: 01
- Thermistor Type: Type 60, PreCon Type III, -30°F to 240°F
- Baud Rate: 9600 bps
- Checksum disabled
- Engineering unit format
- Temperature Scale: Celsius (the I-7005 also supports Fahrenheit)

Default settings for the M-7005 modules are as follows:

- Protocol: Modbus RTU
- Module Address: 01
- Thermistor Type: Type 60, PreCon Type III, -30°F to 240°F for I-7005
- Baud Rate: 9600 bps
- Temperature Scale: Celsius (the M-7005 also supports Fahrenheit for DCON protocol)

## **1.9 Calibration**

**Warning:** It is not recommended that calibration be performed until the process is fully understood.

The calibration procedure is as follows:

- 1. Warm up the module for at least 30 minutes.
- 2. Set the type code to the type you wish to calibrate. Refer to Section 2.12 for details.
- 3. Enable calibration. Refer to Section. 2.24 for details.
- 4. Connect the zero calibration resistor.
- Send the zero calibration command. Refer to Section 2.5 for details.
- 6. Connect the span calibration resistor.
- Send the span calibration command. Refer to Section 2.6 for details.
- 8. Repeat steps 3 to 7 three times.

#### Notes:

- 1. For the I-7005 and M-7005, each channel should be calibrated separately.
- 2. For the I-7005 and M-7005, types 71 to 77 must be calibrated for each channel.
- 3. Calibration resistors are shown on the next page.
- 4. The M-7000 series modules must be switched to the DCON protocol mode before calibrating. Refer to Sections 1.13.1 and 3.6.4 for details of the switching protocol.

# Calibration resistor types used by the I-7005 and M-7005

Туре	Zero Calibration Resistor	Span Calibration Resistor
71	0 Ohms	2700 Ohms
72	0 Ohms	5600 Ohms
73	0 Ohms	12000 Ohms
74	0 Ohms	22000 Ohms
75	0 Ohms	47000 Ohms
76	0 Ohms	91000 Ohms
77	0 Ohms	150000 Ohms

## **1.10 Configuration Tables**

#### **Baud Rate Setting (CC)**

Code	03	04	05	06	07	08	09	0A
Baud rate	1200	2400	4800	9600	19200	38400	57600	115200

**Note:** The data bits are fixed at one start bit, eight data bits, no parity and one stop bit for the I-7000 and M-7000 series.

#### **Temperature Sensor Type Setting (TT)**

Type Code	Temperature Sensor Type	Temperature Range °C
60	PreCon Type III 10K @ 25°C	$-30^{\circ}F \sim 240^{\circ}F$
61	Fenwell Type U 2K @ 25°C	$-50 \sim 150$
62	Fenwell Type U 2K @ 25°C	0~150
63	YSI L Mix 100 @ 25°C	$-80 \sim 100$
64	YSI L Mix 300 @ 25°C	$-80 \sim 100$
65	YSI L Mix 1000 @ 25°C	$-70 \sim 100$
66	YSI B Mix 2252 @ 25°C	$-50 \sim 150$
67	YSI B Mix 3000 @ 25°C	$-40 \sim 150$
68	YSI B Mix 5000 @ 25°C	$-40 \sim 150$
69	YSI B Mix 6000 @ 25°C	$-30 \sim 150$
6A	YSI B Mix 10000 @ 25°C	$-30 \sim 150$
6B	YSI H Mix 10000 @ 25°C	-30 ~ 150
6C	YSI H Mix 30000 @ 25°C	$-10 \sim 200$
70	User-defined	$-50 \sim 150$
71	User-defined	$-50 \sim 150$
72	User-defined	$-50 \sim 150$
73	User-defined	$-50 \sim 150$
74	User-defined	-50 ~ 150
75	User-defined	-50 ~ 150
76	User-defined	-50 ~ 150
77	User-defined	-50 ~ 150

Note: Please refer to Section 1.11 for details of userdefined types.

### **Data Format Setting (FF)**

7	6	5	4	3	2	1	0
FS	CS	reserved			D	F	

Key	Description				
DF	Data format				
	00: Engineering unit				
	01: % of FSR (full scale range)				
	10: 2's complement hexadecimal				
	11: Ohms				
CS	Checksum setting				
	0: Disabled				
	1: Enabled				
FS	This setting is reserved for the I-7005 and				
	M-7005 and should be zero.				

Note: The reserved bits should be zero.

## **Thermistor Type and Data Format Table**

Type Code	Thermistor Type	Data Format	+F.S.	-F.S.
	PreCon Type	Engineering unit	+240.00	-030.00
60	III	% of FSR	+100.00	-012.50
60	10K @ 25°C	2's comp HEX	7FFF	E000
	-35 ~ 115°C	Ohms	+000539.4	+173600.0
	Fenwell U	Engineering unit	+150.00	-050.00
61	2K @ 25°C	% of FSR	+100.00	-033.33
01	$-50 \sim 150^{\circ}C$	2's comp HEX	7FFF	D556
	$-30 \approx 130$ C	Ohms	+000037.2	+134020.0
	Eonwoll II	Engineering unit	+150.00	+000.00
62	Fenwell U	% of FSR	+100.00	+000.00
02	2K @ 25°C 0 ~ 150°C	2's comp HEX	7FFF	0000
	$0 \sim 150$ C	Ohms	+000037.2	+006530.0
	YSI L Mix	Engineering unit	+100.00	-080.00
63	100 @ 25°C	% of FSR	+100.00	-080.00
03	$-80 \sim 100^{\circ}C$	2's comp HEX	7FFF	999A
		Ohms	+000014.3	+014470.0
	YSI L Mix	Engineering unit	+100.00	-080.00
64	300 @ 25°C	% of FSR	+100.00	-080.00
04	$-80 \sim 100^{\circ}$ C	2's comp HEX	7FFF	999A
	00 100 C	Ohms	+000035.8	+067660.0
	YSI L Mix	Engineering unit	+100.00	-070.00
65	1000 @ 25°C	% of FSR	+100.00	-070.00
05	$-70 \sim 100^{\circ}$ C	2's comp HEX	7FFF	A667
	-70 - 100 C	Ohms	+000106.4	+132600.0
	YSI B Mix	Engineering unit	+150.00	-050.00
66		% of FSR	+100.00	-033.33
00	$-50 \sim 150^{\circ}$ C	2's comp HEX	7FFF	D556
	-50 % 150 C	Ohms	+000041.8	+151000.0
	YSI B Mix	Engineering unit	+150.00	-040.00
67		% of FSR	+100.00	-026.67
07	3000 @ 25°C -40 ~ 150°C	2's comp HEX	7FFF	DDDE
		Ohms	+000055.6	+101000.0

Type Code	Thermistor	Data Format	+F.S.	-F.S.
	Туре			
	VCI D Ma	Engineering unit	+150.00	-040.00
(9	YSI B Mix	% of FSR	+100.00	-026.67
68	5000 @ 25°C -40 ~ 150°C	2's comp HEX	7FFF	DDDE
	$-40 \sim 130$ C	Ohms	+000092.7	+168300.0
		Engineering unit	+150.00	-030.00
60	YSI B Mix	% of FSR	+100.00	-020.00
69	6000 @ 25°C -30 ~ 150°C	2's comp HEX	7FFF	E667
	$-50 \sim 150$ C	Ohms	+000111.5	+106200.0
		Engineering unit	+150.00	-030.00
6A	YSI B Mix	% of FSR	+100.00	-020.00
OA	10K @ 25°C -30 ~ 150°C	2's comp HEX	7FFF	E667
	$-50 \sim 150$ C	Ohms	+000185.9	+177000.0
	VCLUM:	Engineering unit	+150.00	-030.00
6B	YSIHMix	% of FSR	+100.00	-020.00
0B	10K @ 25°C -30 ~ 150°C	2's comp HEX	7FFF	E667
	$-50 \sim 150$ C	Ohms	+000237.0	+135200.0
	VCLUM	Engineering unit	+200.00	-010.00
6C	YSIHMix	% of FSR	+100.00	-005.00
OC.	30K @ 25°C -10 ~ 200°C	2's comp HEX	7FFF	F99A
	$-10 \sim 200$ C	Ohms	+000186.7	+158000.0
		Engineering unit	+150.00	-050.00
$70 \sim 77$	User-defined	% of FSR	+100.00	-033.33
/0~//	-50 ~ 150°C	2's comp HEX	7FFF	D556
		Ohms	+000000.0	+000000.0

#### Note:

- 1. For user-defined types, if the resistance is larger than 180000 ohms, then it is treated as under range.
- 2. Refer to Section 1.11 for more information regarding user-defined types.

# Thermistor Over Range/Under Range Reading for the I-7005 and M-7005

	Over Range	Under Range
Engineering Unit	+9999.9	-9999.9
% of FSR	+999.99	-999.99
2's Complement HEX	7FFF	8000

# Thermistor Over Range/Under Range Reading for the M-7005 with Modbus RTU protocol

Over Range	Under Range
7FFFh	8000h

## 1.11 User-defined Types

For a typical thermistor, the relationship between resistance and temperature can be expressed by the Steinhart–Hart equation  $1/T = A + B \ln R_T + C (\ln R_T)^3$ 

where  $R_T$  is the resistance in ohms at temperature T in degrees Kelvin (K = °C + 273.15). The values of A, B, and C are called Steinhart Coefficients. The error of the equation is less than +/- 0.01°C in a 100°C span.

I-7005 and M-7005 support user-defined types by specifying the Steinhart coefficients using the @AASxTttC(data) command, see Section 2.30. The data sent is a 32-bit hexadecimal value in IEEE-754 standard format:

Bits	Description
31 (sign)	0 = positive, 1 = negative
	The exponent base is 2. The actual exponent is calculated by subtracting 127 from the stored value.
	The mantissa is expressed as 1.f where f is the fractional part and is stored in this field.

Example:

For the hexadecimal value C3694000h

- 1. Bit 31 is 1, indicating a negative number.
- 2. The value of bits 30-23 is 10000110 binary or 134 decimal. The exponent is 7, 134-127.
- 3. The mantissa is 1.110100101000000000000 binary.
- 4. Adjust the mantissa for the exponent. The adjusted mantissa is 11101001.010000000000000 binary. That is 233.25 decimal.
- 5. Considering the sign bit. The floating-point number of C3694000h is -233.25.

The following methods can be used to obtain the Steinhart Coefficients of a thermistor.

- 1. Ask the manufacturer. Usually, thermistor manufacturers publish data for the Steinhart Coefficients for their thermisotr products.
- 2. Solve the coefficients by using three known data sets: (R1, T1), (R2, T2) and (R3, T3), which can be obtained by referring to the published Resistance versus Temperature data table of the thermistor. They can be obtained by measurement if no published data table is available. In order to achieve the most accurate results, the following values are recommended: -40°C  $\leq$  T1, T2, T3  $\leq$  150°C and  $|T2 - T1| \leq$  50°C,  $|T3 - T2| \leq$  50°C.

The DCON Utility, available for downloaded from the ICP DAS website (<u>http://www.icpdas.com</u>), can assist with the calculation of the Steinhart Coefficients and the conversion to IEEE-754 format. Documentation for the DCON Utility can be found in the "**Getting Started For I-7000 Series Modules**" manual.

# **1.12 Digital Outputs and Alarms**

The I-7005/M-7005 supports digital outputs that can also be used as alarm outputs. When a host watchdog timeout occurs, the "safe value" is loaded into the digital output ports. The digital output command @AADODD, see Section 2.36, has no effect on the digital output ports until the host watchdog timeout status is cleared. See Section A.2 for host watchdog details. If the host watchdog timeout status has not been cleared when the module is powered on, then the safe value is loaded into the digital output ports. Otherwise, the "power-on value" is loaded into the digital output ports.

The alarm function is performed by comparing the analog input value to the high/low limits stored in the non-volatile memory. The result of the limit check can then be used to control a digital output port. All digital output ports can be used as an alarm output and are programmable. When a digital output port is associated with an alarm, it is not affected by the safe value, power-on value or the digital output command @AADODD. There are two types of alarm:

- 1. Momentary alarm: The alarm status is set only when the analog input value exceeds the alarm limitation. When the analog input value is within the limit, the alarm status is cleared.
- 2. Latched alarm: The alarm status is set when the analog input value exceeds the alarm limitation. After that, it is cleared only when the clear latched alarm command is sent.

Use the set high/low alarm commands, see Sections 2.37 and 2.38, to set the alarm limit, alarm type, alarm checking channel and alarm port.

## 1.13 M-7000 Notes

The main difference between the I-7000 and M-7000 series is that the M-7000 series has additional support for the Modbus RTU communication protocol, which is the default protocol of the M-7000 series. The communication Baud Rates for the Modbus RTU protocol can be in the range of 1200 bps to 115200 bps, and the parity, data and stop bits are fixed as no parity, 8 data bits and 1 stop bit.

Modbus functions supported by the module are described in Chapter 3.

## 1.13.1 Protocol Switching

To switch to the DCON protocol:

- Uses sub-function 06h of the function 46h and set byte 8 to a value of 1. See Section 3.6.4 for details.
- 2. After a power-on reset, the communication protocol will be changed to DCON.

To switch to the Modbus RTU protocol:

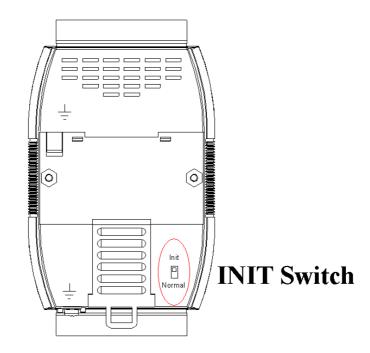
- 1. Sends the \$AAPN command and set N to a value of 1. Note that for the M-7005, the slide switch on the rear side of the module should be set to the INIT position, see the figure on the next page. See Section 2.19 for details.
- 2. After a power-on reset, the communication protocol will be changed to the Modbus RTU protocol.

### 1.13.2 INIT Mode

When the module is powered on, with the rear slide switch set to the INIT position as shown in the figure below for the M-7005, the module is in INIT mode, (see Section A.1 for details), and the communication settings are as follows:

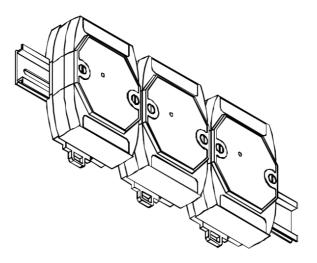
- 1. Address: 00
- 2. Baud Rate: 9600 bps
- 3. No checksum
- 4. Protocol: DCON

If communication with the module is not possible, set the module to the INIT mode and use the above settings to communicate with the module. To read the current settings, send the commands \$AA2, (see Section 2.7), and \$AAP, (see Section 2.18). To set new settings, send the commands %AANNTTCCFF, (see Section 2.1) and \$AAPN, (see Section 2.19). The new communication settings will be effective after the next power-on reset.



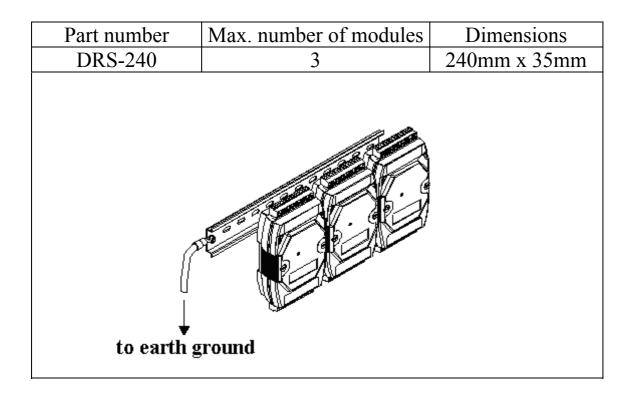
## 1.14 Mounting

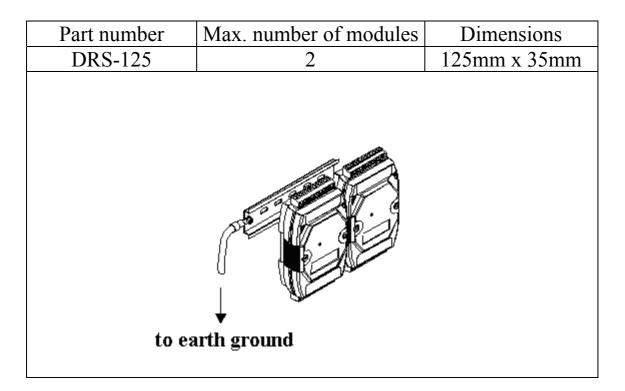
### 1.14.1 Din-Rail Mounting



There are three new DIN rail models available. Each is made of stainless steel, which is stronger than those made of aluminum. There is a screw at one end and a ring terminal is included so that it can be easily connected to the earth ground. The three new DIN rail models are as follows.

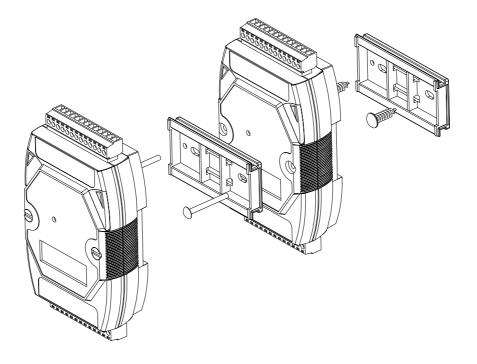
Part number	Max. number of modules	Dimensions
DRS-360	5	360mm x 35mm
to earth gro	ound	



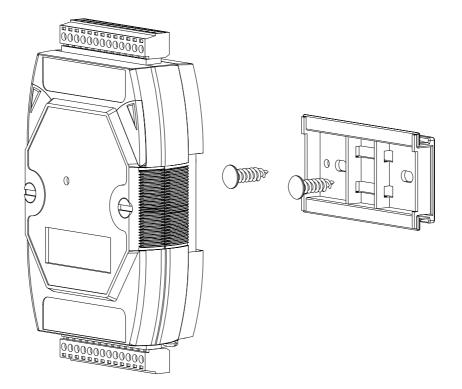


Note: It is recommended that a 16 - 14 AWG wire is used to connect the DIN rail to the earth ground.

## 1.14.2 Piggyback Mounting



### 1.14.3 Wall Mounting



# **1.15 Technical Support**

Should you encounter any problems while using the I-7000 and M-7000 module, and are unable to find the help you need in this manual or on our website, please contact ICP DAS Product Support.

Email: <u>support@icpdas.com</u>

Website: http://www.icpdas.com/service/support.htm

When requesting technical support, be prepared to provide the following information about your system:

- 1. Module name and serial number: The serial number can be found printed on the barcode label attached to the cover of the module.
- 2. Firmware version: See Section 2.15 and 3.6.7 for information regarding the command used to identify the firmware version.
- 3. Host configuration (type and operating system)
- 4. If the problem is reproducible, please give full details describing the procedure used to reproduce the problem.
- 5. Any specific error messages displayed. If a dialog box with an error message is displayed, please include the full text of the dialog box, including the text in the title bar.
- 6. If the problem involves other programs or hardware devices, please describe the details of the problem in full.
- 7. Any comments and suggestions related to the problem are welcome.

ICP DAS will reply to your request by email within three business days.

# 2. DCON Protocol

All communication with I-7000 modules consists of commands generated by the host and responses transmitted by the I-7000 modules. Each module has a unique ID number that is used for addressing purposes and is stored in non-volatile memory. The ID is 01 by default and can be changed using a user command. All commands to the modules contain the ID address, meaning that only the addressed module will respond. The only exception to this is commands  $\#^*$  (Section 2.2) and  $\sim^{**}$  (Section 2.43), which are sent to all modules, but in both of these cases, the modules do not reply to the command.

## **Command Format:**

Leading Character		Command	[CHKSUM]	CR
----------------------	--	---------	----------	----

#### **Response Format:**

Leading Module Character Address	Data	[CHKSUM]	CR
-------------------------------------	------	----------	----

CHKSUM	A 2-character checksum which is present
	when the checksum setting is enabled. See
	Sections 1.10 (Data Format Setting) and 2.1
	for details.
CR	End of command character, carriage return
	(0x0D)

## **Checksum Calculation:**

- 1. Calculate the ASCII code sum of all the characters in the command/response string except for the carriage return character (CR).
- 2. The checksum is equal to the sum masked by 0FFh.

## Example:

Command string: \$012(CR)

- 1. Sum of the string = "\$"+"0"+"1"+"2" = 24h+30h+31h+32h = B7h
- 2. Therefore the checksum is B7h, and so CHKSUM = "B7"
- 3. The command string with the checksum = 012B7(CR)

Response string: !01200600(CR)

- 1. Sum of the string = "!"+"0"+"1"+"2"+"0"+"0"+"6"+"0"+"0" = 21h+30h+31h+32h+30h+30h+36h+30h+30h = 1AAh
- 2. Therefore the checksum is AAh, and so CHKSUM = "AA"
- 3. The response string with the checksum = !01200600AA(CR)

## Note:

All characters should be in upper case.

General Command Sets			
Command	Response	Description	Section
%AANNTTCCFF	!AA	Sets the module configuration	2.1
#**	No Response	Synchronized sampling	2.2
#AA	>(Data)	Reads the analog inputs of all channels	2.3
#AAN	>(Data)	Reads the analog input of a specified channel	2.4
\$AA0Ci	!AA	Performs a single channel zero calibration	2.5
\$AA1Ci	!AA	Performs a single channel span calibration	2.6
\$AA2	!AANNTTCCFF	Reads the module configuration	2.7
\$AA4	>AAS(Data)	Reads the synchronized data	2.8
\$AA5	!AAS	Reads the module reset status	2.9
\$AA5VV	!AA	Enables/Disables a channel	2.10
\$AA6	!AAVV	Reads the channel enabled/disabled status	2.11
\$AA7CiRrr	!AA	Sets a single channel range configuration	2.12
\$AA8Ci	!AACiRrr	Reads a single channel range configuration	2.13
\$AAB	!AANN	Reads the channel diagnostic status	2.14
\$AAF	!AA(Data)	Reads the firmware version	2.15
\$AAI	!AAS	Reads the INIT status	2.16
\$AAM	!AA(Data)	Reads the module name	2.17
\$AAP	!AASC	Reads the communication protocol	2.18
\$AAPN	!AA	Sets the communication protocol	2.19
\$AAS0	!AA	Internal Calibration	2.20
\$AAS1	!AA	Reloads the default calibration parameters	2.21
~AAD	!AAT	Reads the temperature scaling	2.22
~AADT	!AA	Sets the temperature scaling to either °C or °F	2.23
~AAEV	!AA	Enables/Disables calibration	2.24
~AAI	!AA	Soft INIT	2.25
~AAO(Name)	!AA	Sets the module name	2.26
~AATnn	!AA	Sets the soft INIT timeout	2.27

User-defined Thermistor Type Setting Command Sets			
Command	Response	Description	Section
@AAGxTtt	!AA(data)	Reads the Steinhart coefficient of a user-defined type	2.28
@AARTTttR(data)	!AA(data)	Reads the temperature corresponding to the resistance of a user-defined type	2.29
@AASxTttC(data)	!AA	Sets the Steinhart coefficient of a user-defined type	2.30

Digital Output and Alarm Command Sets				
Command	Response	Description	Section	
@AACHCi	!AA	Clears the high latched alarm	2.31	
@AACLCi	!AA	Clears the low latched alarm	2.32	
@AADHCi	!AA	Disables the high alarm	2.33	
@AADI	!AAOO	Reads the DO status	2.34	
@AADLCi	!AA	Disables the low alarm	2.35	
@AADODD	!AA	Sets the DO status	2.36	
@AAHI(data)CiTOj	!AA	Sets the high alarm	2.37	
@AALO(data)CiTOj	!AA	Sets the low alarm	2.38	
@AARAOj	!AAHHLL	Reads the current alarms associated with a DO port	2.39	
@AARHCi	!AA(data)SOj	Reads the high alarm setting	2.40	
@AARLCi	!AA(data)Soj	Reads the low alarm setting	2.41	
@AAROOj	!AAHHLL	Reads the alarms associated with a DO port	2.42	

Host Watchdog Command Sets			
Command	Response	Description	Section
$\sim^{**}$	No Response	Host is OK	2.43
~AA0	!AASS	Reads the host watchdog status	2.44
~AA1	!AA	Resets the host watchdog status	2.45
~AA2	!AAETT	Reads the host watchdog timeout settings	2.46
~AA3ETT	!AA	Sets the host watchdog timeout settings	2.47
~AA4	!AAPPSS	Reads the power-on value and safe value	2.48
~AA5PPSS	!AA	Sets the power-on value and safe value	2.49

## 2.1 %AANNTTCCFF

#### **Description:**

Sets the configuration of an analog input module.

#### Syntax:

#### %AANNTTCCFF[CHKSUM](CR)

- % Delimiter character
- AA Address of the module to be configured in hexadecimal format (00 to FF)
- NN New address of the module in hexadecimal format (00 to FF)
- TT New type code, see Section 1.10 for details. Not used by the I-7005 and M-7005. For the I-7005 and M-7005, use the \$AA7CiRrr command to set the type of each channel, see Section 2.12 for details.
- CC New Baud Rate code, see Section 1.10 for details. For the I-7005 and M-7005, the rear slide switch must be moved to the INIT position in order to change Baud Rates. See Section A.1 for details.
- FF Used to set the data format, checksum, and filter settings (Section 1.10). For the I-7005 and M-7005, the rear slide switch must be moved to the INIT position in order to change the checksum setting. See Section A.1 for details.

### **Response:**

Valid Command: **!AA[CHKSUM](CR)** Invalid Command: **?AA[CHKSUM](CR)** 

! Delimiter for a valid command

- Delimiter for an invalid command. If the Baud
   Rate or checksum settings are changed without
   switching the rear slide switch to the INIT position,
   the module will return an invalid command.
- AA Address of the module in hexadecimal format (00 to FF)

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## **Examples:**

Command: %0102200600 Response: !02
Changes the address of module 01 to 02. The module returns a valid response.
Command: %0202200603 Response: !02
Sets the data format of module 02 to be 3 (Ohms). The module returns a valid response.
Command: %0101200A00 Response: ?01
Changes the Baud Rate of module 01 to 115200bps. The module returns an invalid command, because it is not in INIT\* mode.

Command: %0101200A00 Response: !01 Changes the Baud Rate of module 01 to 115200bps and the module is in INIT\* mode. The module returns a valid response.

### **Related Commands:**

Section 2.7 \$AA2, Section 2.25 ~AAI, Section 2.27 ~AATnn

## **Related Topics:**

Section 1.10 Configuration Tables, Section A.1 INIT\* pin Operation

## Notes:

- 1. Changes to the address, type code and data format settings take effect immediately after a valid command is received. Changes to the Baud Rate and checksum settings take effect on the next power-on reset.
- 2. For the I-7005 and M-7005, changing the Baud Rate and checksum settings can be achieved by software only and is performed by using the following commands:
  - I. Send a ~AATnn command. See Section 2.27 for details.
  - II. Send a ~AAI command. See Section 2.25 for details.

III. Send a %AANNTTCCFF command.

If the command is valid, the Baud Rate and checksum settings will be changed after the module responds with !AA.

# 2.2 #\*\*

## **Description:**

When the command is received, it will allow all analog input modules to read data from all input channels and will store the data for later retrieval.

## Syntax:

#### #\*\*[CHKSUM](CR)

# Delimiter character\*\* Synchronized sampling command

### **Response:**

There is no response with this command. To access the data, another command, \$AA4, must be sent, see Section 2.8 for details.

## **Examples:**

Command: #\*\* No response Sends the synchronized sampling command. Command: \$014 Response: >011+025.123 Sends a command to read the synchronized data. The status byte of the response is 1, which means that it is the first time the synchronized data has been read after the previous #\*\* command. Command: \$014 Response: >010+025.123 Sends a command to read the synchronized data. The status byte of the response is 0, which means that it is **NOT** the first time the synchronized data has been read after the previous #\*\* command.

### **Related Commands:**

Section 2.8 \$AA4

# 2.3 #AA

### **Description:**

Reads the data from all analog input channels.

## Syntax:

#### #AA[CHKSUM](CR)

#	Delimiter character
AA	Address of the module to be read (00 to FF)

### **Response:**

Valid Co	mmand: >(Data)[CHKSUM](CR)
Invalid C	Command: ?AA[CHKSUM](CR)
>	Delimiter character for a valid command
?	Delimiter character for an invalid command
(Data)	Data from all analog input channels, see Section
	1.10 for the data format. For both the I-7005
	and M-7005, data from disabled channels is
	filled with space characters.
AA	Address of the responding module (00 to FF)

Command: #01 Response: >+026.35 Reads module 01 and receives the data in engineering format.
Command: #02 Response: >4C53 Reads module 02 and receives the data in hexadecimal format.
Command: #03 Response: >-0000 Reads module 03 and the data is under range.
Command: #04 Response: >+025.12+054.12+150.12 Reads module 04, an I-7033, and receives the data from 3 channels.

### **Related Commands:**

Section 2.1 %AANNTTCCFF, Section 2.7 \$AA2

## **Related Topics:**

Section 1.10 Configuration Tables

# 2.4 #AAN

### **Description:**

Reads the analog input of channel N.

### Syntax:

#### #AAN[CHKSUM](CR)

#	Delimiter character
AA	Address of the module to be read (00 to FF)
Ν	The channel to be read, zero based.

#### **Response:**

Valid Co	mmand: >(Data)[CHKSUM](CR)
Invalid C	Command: <b>?AA[CHKSUM](CR)</b>
>	Delimiter character for a valid command
?	Delimiter character for an invalid command. An
	invalid command is returned if the specified
	channel is incorrect.
(Data)	Analog input data of the specified channel, see
	Section 1.10 for the data format. For the I-7005
	and M-7005, if the specified channel is disabled,
	then the data field will be filled with space
	characters.
AA	Address of the responding module (00 to FF)

Command: #032 Response: >+025.13 Reads data from channel 2 of module 03. Command: #029 Response: ?02 Reads data from channel 9 of module 02. An error is returned because channel 9 is invalid.

### **Related Commands:**

Section 2.1 %AANNTTCCFF, Section 2.7 \$AA2

### **Related Topics:**

Section 1.10 Configuration Tables

# 2.5 \$AA0Ci

### **Description:**

Performs a zero calibration on the specified channel.

## Syntax:

## \$AA0Ci[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be calibrated (00 to FF)
0	Command for the zero calibration
Ci	Specifies the channel to be calibrated

### Response:

#### Valid Command: **!AA[CHKSUM](CR)** Invalid Command: **?AA[CHKSUM](CR)**

! Delimiter character for a valid comman
--

? Delimiter character for an invalid command. An invalid command is returned if the specified channel is incorrect.

AA Address of the responding module (00 to FF)

Command: \$010C0 Response: !01

Performs a zero calibration on channel 0 of module
01 and returns a valid response.

Command: \$020C5 Response: !02

Performs a zero calibration on channel 5 of module
02 and returns a valid response.

Command: \$030C1 Response: ?03

Performs a zero calibration on channel 1 of module
03. An invalid command is returned because the "enable calibration" command was not sent in advance.

### **Related Commands:**

Section 2.6 \$AA1Ci, Section 2.24 ~AAEV

## **Related Topics:**

Section 1.9 Calibration

### Notes:

The "enable calibration" command, ~AAEV, must be sent before this command is used, see Section 1.9 for details.

# 2.6 \$AA1Ci

#### **Description:**

Performs a span calibration on the specified channel.

### Syntax:

### \$AA1Ci[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be calibrated (00 to FF)
1	Command for the span calibration
Ci	Specifies the channel to be calibrated

### **Response:**

### Valid Command: **!AA[CHKSUM](CR)** Invalid Command: **?AA[CHKSUM](CR)**

!	Delimiter character for a valid command
---	---

? Delimiter character for an invalid command. An invalid command is returned if the specified channel is incorrect.

AA Address of the responding module (00 to FF)

Command: \$011C0 Receive: !01

Performs a span calibration on channel 0 of module
01 and returns a valid response.

Command: \$021C5 Receive: !02

Performs a span calibration on channel 5 of module
02 and returns a valid response.

Command: \$031C1 Receive: ?03

Performs a span calibration on channel 1 of module
03. An invalid command is returned because the "enable calibration" command was not sent in advance.

### **Related Commands:**

Section 2.5 \$AA0Ci, Section 2.24 ~AAEV

## **Related Topics:**

Section 1.9 Calibration

### Notes:

The "enable calibration" command, ~AAEV, must be sent before this command is used, see Section 1.9 for details.

# 2.7 \$AA2

### **Description:**

Reads the module configuration.

## Syntax:

#### \$AA2[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be read (00 to FF)
2	Command to read the module configuration

#### **Response:**

Valid Co	mmand: !AATTCCFF[CHKSUM](CR)
Invalid C	command: <b>?AA[CHKSUM](CR)</b>
!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)
TT	Type code of the module, see Section 1.10 for
	details.
CC	Baud Rate code of the module, see Section 1.10
	for details.
FF	Data format, checksum settings and filter
	settings of the module, see Section 1.10 for
	details.

Command: \$012Response: !01200600Reads the configuration of module 01.Command: \$022Reads the configuration of module 02.

### **Related Commands:**

Section 2.1 %AANNTTCCFF

### **Related Topics:**

Section 1.10 Configuration Tables

# 2.8 \$AA4

## **Description:**

Reads the synchronized data that was retrieved by the last #\*\* command.

## Syntax:

#### \$AA4[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be read (00 to FF)
4	Command to read the synchronized data

### **Response:**

Valid Command:	>AAS(Data)[CHKSUM](CR)
Invalid Command:	?AA[CHKSUM](CR)

!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)
S	Status of the synchronized data
	1: first read
	0: not the first read
(Data)	Synchronized data. See Section 1.10 for the
	data format. For the I-7005 and M-7005
	modules, data from disabled channels is filled
	with space characters.

Command: \$014 Response: ?01 Reads the synchronized data for module 01. An invalid command is returned because the  $\#^{**}$ command has not been issued in advance. Command: #\*\* No response Sends the synchronized sampling command. Command: \$014 Response: >011+025.56 Reads the synchronized data for module 01. The module returns the synchronized data and sets the status byte to 1 to indicate that this is the first time the synchronized data has been read. Command: \$014 Response: >010+25.56 Reads the synchronized data for module 01. The module returns the synchronized data and sets the status byte to 0 to indicate that the synchronized data has been read

## **Related Commands:**

Section 2.2 #\*\*

# 2.9 \$AA5

## **Description:**

Reads the reset status of a module.

## Syntax:

## \$AA5[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be read (00 to FF)
5	Command to read the module reset status

### **Response:**

Valid Com	nmand: <b>!AAS[CHKSUM](CR)</b>
Invalid Co	mmand: <b>?AA[CHKSUM](CR</b> )
! ]	Delimiter character for a valid command
? ]	Delimiter character for an invalid command
AA A	Address of the responding module (00 to FF)
S I	Reset status of the module
]	1: This is the first time the command has been
	sent since the module was powered on.
(	): This is not the first time the command has
	been sent since the module was powered on,
	which denotes that there has been no module
	reset since the last \$AA5 command was sent.

Command: \$015 Response: !011 Reads the reset status of module 01. The response shows that it is the first time the \$AA5 command has been sent since the module was powered-on. Command: \$015 Response: !010 Reads the reset status of module 01. The response shows that there has been no module reset since the last \$AA5 command was sent.

# 2.10 \$AA5VV

### **Description:**

Specifies the channels to be enabled.

### Syntax:

#### \$AA5VV[CHKSUM](CR)

- \$ Delimiter character
- AA Address of the module to be set (00 to FF)
- 5 Command to set the channels to enabled
- VV A two-digit hexadecimal value, where bit 0 corresponds to channel 0, bit 1 corresponds to channel 1, etc. When the bit is 1, it denotes that the channel is enabled, and 0 denotes that the channel is disabled.

### **Response:**

Valid Command:	!AA[CHKSUM](CR)
Invalid Command:	?AA[CHKSUM](CR)

- Delimiter character for a valid command
   Delimiter character for an invalid command. An invalid command is returned if an attempt is made to enable a channel that is not present.
- AA Address of the responding module (00 to FF)

Command: \$0153A Response: !01

Enables channels 1, 3, 4, and 5 and disables all other channels of module 01. The module returns a valid response.

Command: \$016 Response: !013A

Reads the channel status of module 01. The module returns a response of 3A, which denotes that channels

1, 3, 4, and 5 are enabled and all other channels are disabled.

## **Related Commands:**

Section 2.11 \$AA6

### Notes:

It is recommended that only the channels to be used are enabled.

# 2.11 \$AA6

### **Description:**

Reads the enabled/disabled status of each channel.

## Syntax:

### \$AA6[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be read (00 to FF)
6	Command to read the channel status

### **Response:**

Valid Cor	nmand: <b>!AAVV[CHKSUM](CR)</b>
Invalid Co	ommand: <b>?AA[CHKSUM](CR</b> )
!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)
VV	A two-digit hexadecimal value, where bit 0
	corresponds to channel 0, bit 1 corresponds to
	channel 1, etc. When the bit is 1, it denotes that
	the channel is enabled, and 0 denotes that the
	channel is disabled.

Command: \$0153AResponse: !01Enables channels 1, 3, 4, and 5 and disables all other<br/>channels of module 01. The module returns a valid<br/>response.Command: \$016Response: !013A

Response: 1013A Reads the channel status of module 01 and returns a response of 3A, which denotes that channels 1, 3, 4, and 5 are enabled and all other channels are disabled.

### **Related Commands:**

Section 2.10 \$AA5VV

# 2.12 \$AA7CiRrr

### **Description:**

Sets the type code of a channel.

### Syntax:

#### **\$AA7CiRrr[CHKSUM](CR)**

•	
\$	Delimiter character
AA	Address of the module to be set (00 to FF)
7	Command to set the channel range code
Ci	i specifies the input channel to be set (0-7)
Rrr	rr represents the type code of the channel to be
	set. Refer to the Temperature Sensor Type
	Setting table in Section 1.10.

### **Response:**

Valid cor	nmand: <b>!AA [CHKSUM](CR)</b>
Invalid co	ommand: <b>?AA[CHKSUM](CR)</b>
!	Delimiter character for a valid command
?	Delimiter character for an invalid command or
	invalid type code
AA	Address of the responding module (00 to FF)

Command: \$017C0R60 Response: !01
Sets the type code for channel 0 of module 01 to be 60 and the module returns a valid response.
Command: \$027C5R72 Response: !02
Sets the type code for channel 5 of module 02 to be 72 and the module returns a valid response.
Command: \$037C1R30 Response: ?03
Sets the type code for channel 1 of module 03 to be 30. The module returns an invalid response because the type code is invalid.

## **Related Commands:**

Section 2.13 \$AA8Ci

## **Related Topics:**

Section 1.10 Configuration Tables

### Notes:

For the I-7005 and M-7005, when the type code of a channel is changed, the high/low alarms of the channel are disabled.

# 2.13 \$AA8Ci

## **Description:**

Reads the type code information of a channel.

## Syntax:

## \$AA8Ci[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be read (00 to FF)
8	Command to read the type code of a channel
Ci	Specifies which channel to access for the type
	code information (i = $0 \sim 7$ )

## **Response:**

#### Valid command: **!AACiRrr[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel
- AA Address of the responding module (00 to FF)
- Ci Specifies which input channel the type code information relates to.
- Rrr Represents the type code of the specified input channel. Refer to the Temperature Sensor Type Setting table in Section 1.10.

Command: \$018C0 Response: !01C0R70 Reads the input range of channel 0 of module 01 and returns 70.

### **Related Commands:**

Section 2.12 \$AA7CiRrr

### **Related Topics:**

Section 1.10 Configuration Tables

# 2.14 \$AAB

### **Description:**

Diagnoses the analog inputs for over-range, under-range, and wire opening conditions.

## Syntax:

#### \$AAB[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be diagnosed (00 to FF)
В	Command to diagnose the analog inputs

## **Response:**

### Valid command: **!AANN[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

! Delimiter character for a valid command

? Delimiter character for an invalid command

- AA Address of the responding module (00 to FF)
- NN Represents the diagnostic results of all the analog input channels (00 to FF), where bit 0 corresponds to channel 0, bit 1 corresponds to channel 1, etc. When the bit is 1 it denotes that the channel is enabled and it is in either overrange, under-range or wire opening condition. If the bit is 0 it denotes that the channel is disabled or normal.

Command: \$01B Response: !0101 Diagnoses the analog inputs of module 01. The module returns a valid response denoting that channel 1 is in either over-range, under-range or wire opening condition.

# 2.15 \$AAF

## **Description:**

Reads the firmware version of a module.

# Syntax:

## \$AAF[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be read (00 to FF)
F	Command to read the firmware version

### **Response:**

Valid cor	mand: !AA(Data)[CHKSUM](CR)	
Invalid co	mmand: <b>?AA[CHKSUM](CR)</b>	
!	Delimiter character for a valid command	
?	Delimiter character for an invalid command	
AA	Address of the responding module (00 to FF	)
(Data)	Firmware version string of the module	

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Response: !01A2.0		
of module 01, and shows		
Response: !02B1.1		
Reads the firmware version of module 02, and shows		

# 2.16 \$AAI

## **Description:**

Reads the INIT status of a module.

#### Syntax:

#### \$AAI[CHKSUM](CR)

\$	Delimiter character
AA	Address of the module to be diagnosed (00 to FF)
Ι	Command to read the module INIT status

#### **Response:**

Valid cor	nmand: <b>!AAS[CHKSUM](CR)</b>
Invalid co	ommand: <b>?AA[CHKSUM](CR)</b>
!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)
S	INIT switch status of the module
	0: The INIT switch is moved to the INIT position
	1: The INIT switch is moved to the Normal position

Command: \$011 Response: !010 Reads the INIT status of module 01. The response shows that the INIT switch is moved to the INIT position.

# 2.17 \$AAM

## **Description:**

Reads the name of a module.

### Syntax:

\$AAM[CHKSUM](CR)		
\$	Delimiter character	
AA	Address of the module to be read (00 to FF)	
Μ	Command to read the module name	

### **Response:**

Valid con	nmand: <b>!AA(Data)[CHKSUM](CR)</b>
Invalid c	ommand: <b>?AA[CHKSUM](CR)</b>
!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)
(Name)	Name string of the module

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: \$01M Response: !017005 Reads the module name of module 01 and returns the name "7005".

## **Related Commands:**

Section 2.26 ~AAO(Name)

# 2.18 \$AAP

### **Description:**

Reads the communication protocol information.

### Syntax:

\$AAP[CHKSUM](CR)		
\$	Delimiter character	
AA	Address of the module to be read (00 to FF)	
Р	Command to read the communication protocol	

### **Response:**

Valid Re	sponse: !AASC[CHKSUM](CR)
Invalid R	esponse: ?AA[CHKSUM](CR)
!	Delimiter character for a valid response
?	Delimiter character for an invalid response
AA	Address of the responding module (00 to FF)
S	The protocols supported by the module
	0: only DCON protocol is supported
	1: both the DCON and Modbus RTU protocols
	are supported
С	Current protocol saved in EEPROM that will be
	used at the next power on reset
	0: the protocol set in EEPROM is DCON
	1: the protocol set in EEPROM is Modbus RTU

Command: \$01P Response: !0110 Reads the communication protocol of module 01 and returns a response of 10 meaning that it supports both the DCON and Modbus RTU protocols and the protocol that will be used at the next power on reset is DCON.

### **Related Commands:**

Section 2.19 \$AAPN

#### Note:

This command is only applicable to the M-7005.

# 2.19 \$AAPN

### **Description:**

Sets the communication protocol.

### Syntax:

\$AAPN[	CHKSUM](CR)		
\$	Delimiter character		
AA	Address of the module to be read (00 to FF)		
Р	Command to set the communication protocol		
Ν	0: DCON protocol		
	1: Modbus RTU protocol		
	Before using this command, the rear slide switch		
	must be in the INIT position for M-7005, see		
Section A.1 for details. The new protocol is			
	saved in the EEPROM and will be effective after		
	the next power on reset.		

### **Response:**

Valid Res	ponse:	!AA[CHKSUM](CR)
Invalid Re	esponse:	?AA[CHKSUM](CR)
!	Delimiter	character for a valid response
?	Delimiter	character for an invalid response
AA	Address of	of the responding module (00 to FF)

Command: \$01P1 Response: ?01 Sets the communication protocol of module 01 to Modbus RTU and returns an invalid response because the module is not in INIT mode. Command: \$01P1 Response: !01 Sets the communication protocol of module 01 to Modbus RTU and returns a valid response.

## **Related Commands:**

Section 2.18 \$AAP

### **Related Topics:**

Section A.1 INIT Mode

## Note:

This command is only applicable to the M-7005.

# 2.20 \$AAS0

## **Description:**

Performs an internal calibration on a module.

## Syntax:

## \$AAS0[CHKSUM](CR)

- \$ Delimiter character
- AA Address of the module to be calibrated (00 to FF)
- S0 Command to perform the internal calibration

## Response:

Valid co	ommand:	!AA[CHKSUM](CR)
Invalid	command:	?AA[CHKSUM](CR)
!	Delimiter	character for a valid command
?	Delimiter	character for an invalid command
AA	Address of	of the responding module (00 to FF)

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: \$01S0 Response: !01 Sends the command to perform an internal calibration on module 01 and returns a valid response.

## **Related Commands:**

Section 2.21 \$AAS1

# 2.21 \$AAS1

## **Description:**

Reloads the factory default calibration parameters, including the internal calibration parameters.

## Syntax:

### \$AAS1[CHKSUM](CR)

\$ Delimiter character
------------------------

- AA Address of the module to have the default parameters reloaded (00 to FF)
- S1 Command to reload the factory default calibration parameters

## Response:

Valid command:	!AA[CHKSUM](CR)
Invalid command:	?AA[CHKSUM](CR)
1 Delimiter	aborator for a valid com

!	Delimiter chara	cter for a valid co	ommand
9	Delimitar abore	aton for an invali	d a a ma ma a ma

? Delimiter character for an invalid command

AA Address of the responding module (00 to FF)

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: \$01S1 Response: !01 Sends the command to reload the factory default calibration parameters for module 01 and returns a valid response.

### **Related Commands:**

Section 2.20 \$AAS0

#### **Related Topics:** Section 1.9 Calibration

# 2.22 ~AAD

## **Description:**

Reads the temperature scale information of a module.

## Syntax:

### ~AAD[CHKSUM](CR)

~	Delimiter character
AA	Address of the module to be read (00 to FF)
D	Command to read the temperature scale

### **Response:**

Valid Command:	<b>!AAT[CHKSUM](CR)</b>	
Invalid Command:	?AA[CHKSUM](CR)	
! Delimiter	character for a valid command	
? Delimiter	character for an invalid command	
AA Address of	of the responding module (00 to FF)	
T Temperat	Temperature scale	
0: the ten	0: the temperature scale is Celsius.	
1: the ten	perature scale is Fahrenheit.	

Command: ~01D Response: !010 Reads the temperature scale of module 01 and returns Celsius. Command: ~02D Response: !021 Reads the temperature scale of module 02 and returns Fahrenheit.

## **Related Commands:**

Section 2.23 ~AADT

#### Notes:

The default temperature scale is Celsius.

# 2.23 ~AADT

## **Description:**

Sets the temperature scale of a module to Celsius or Fahrenheit.

## Syntax:

### ~AADT[CHKSUM](CR)

Delimiter character
Address of the module to be set (00 to FF)
Command to set the temperature scale
C: set the temperature scale to Celsius.
F: set the temperature scale to Fahrenheit.

## **Response:**

Valid Co	mmand:	<b>!AA[CHKSUM](CR)</b>
Invalid C	ommand:	<b>?AA[CHKSUM](CR)</b>
!	Delimiter	character for a valid command
?	Delimiter	character for an invalid command
AA	Address of	f the responding module (00 to FF)

Command: ~01DC Response: !01 Sets the temperature scale of module 01 to Celsius, and returns a valid response. Command: ~02DF Response: !02 Sets the temperature scale of module 02 to Fahrenheit, and returns a valid response.

## **Related Commands:**

Section 2.22 ~AAD

### Notes:

- 1. The default temperature scale is Celsius.
- The commands affected are #AA, #AAN, @AARTTttR(Data), @AAHI(data)CiTOj, @AALO(data)CiTOj.

# 2.24 ~AAEV

### **Description:**

Enables/Disables the module calibration.

## Syntax:

### ~AAEV[CHKSUM](CR)

- ~ Delimiter character
- AA Address of the module to be enabled/disabled (00 to FF)
- E Command to enable/disable calibration
- V 1: enable calibration
  - 0: disable calibration

## **Response**:

### Valid Command: **!AA[CHKSUM](CR)** Invalid Command: **?AA[CHKSUM](CR)**

!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)

Command: \$010Response: ?01Sends the command to perform a span calibration on<br/>module 01. An invalid response is returned because<br/>the "enable calibration" command has not yet been<br/>sent.Command: ~01E1Response: !01Enables calibration on module 01 and returns a valid

response. Command: \$010 Response: !01 Sends the command to perform a span calibration on module 01 and returns a valid response.

### **Related Commands:**

Section 2.5 \$AA0Ci, Section 2.6 \$AA1Ci

### **Related Topics:**

Section 1.9 Calibration

# 2.25 ~AAI (Soft INIT command)

## **Description:**

The Soft INIT command is used to enable modification of the Baud Rate and checksum settings using software only.

## Syntax:

### ~AAI[CHKSUM](CR)

$\sim$	Delimiter character
AA	Address of the module to be set (00 to FF)
Ι	Command to set the Soft INIT

### **Response:**

Valid comm	and: <b>!AA[CHKSUM](CR)</b>
Invalid com	mand: <b>?AA[CHKSUM](CR)</b>
! De	elimiter character for a valid command
? De	elimiter character for an invalid command
AA Ac	ldress of the responding module (00 to FF)

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: ~01I Response: !01 Sets the soft INIT of module 01 and returns a valid response.

## **Related Commands:**

Section 2.1 %AANNTTCCFF, Section 2.27 ~AATnn

### **Related Topics:**

Section A.1 INIT\* Pin Operation

### Notes:

The ~AATnn command should be sent prior to sending this command, see Section 2.27 for details.

## 2.26 ~AAO(Name)

### **Description:**

Sets the name of a module.

### Syntax:

#### ~AAO(Name)[CHKSUM](CR)

- ~ Delimiter character
- AA Address of the module to be set (00 to FF)
- O Command to set the module name
- (Name) New name of the module (max. 6 characters).

### **Response:**

Valid con	nmand:	!AA[CHKSUM](CR)
Invalid c	ommand:	?AA[CHKSUM](CR)
!	Delimiter	character for a valid command
?	Delimiter	character for an invalid command
AA	Address of	of the responding module (00 to FF)

Command: ~01O7005N Response: !01 Sets the name of module 01 to be "7005N" and returns a valid response. Command: \$01M Response: !017005N Reads the name of module 01 and returns the name "7005N".

## **Related Commands:**

Section 2.17 \$AAM

## 2.27 ~AATnn

## **Description:**

Sets the soft INIT timeout value.

### Syntax:

## ~AATnn[CHKSUM](CR)

~	Delimiter character
AA	Address of the module to be set (00 to FF)
Т	Command to set the soft INIT timeout
nn	Two hexadecimal digits representing the timeout
	value in seconds. The maximum timeout value
	is 60 seconds. When changing the Baud Rate or
	checksum settings without altering the INIT*
	status, the ~AAI and %AANNTTCCFF
	commands should be sent consecutively and the
	time interval between the two commands should
	be less than the soft INIT timeout. If the soft
	INIT timeout is 0, then the Baud Rate and
	checksum settings cannot be changed using
	software only. The power-on reset value of the
	soft INIT timeout is 0.

### **Response:**

Valid command: !AA[CHKSUM](CR)
Invalid command: ?AA[CHKSUM](CR)
! Delimiter character for a valid command
? Delimiter character for an invalid command
AAddress of the responding module (00 to FF)

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: ~01I	Response: !01
Sets the soft INIT timeou	it value of module 01 and
returns a valid response.	
Command: %0101000700	Response: ?01
Attempts to change the E	Baud Rate of module 01 to
19200 without first alteri	ng the INIT * status. The
module returns an invalid	d response because the soft
INIT timeout value is 0.	
Command: ~01T10	Response: !01
Sets the soft INIT timeou	it value of module 01 to 16
seconds and returns a val	lid response.
Command: ~01I	Response: !01
Sets the soft INIT of mod	dule 01 and returns a valid
response.	
Command: %0101000700	Response: !01
Changes the Baud Rate of	of module 01 to 19200
without first altering INI	T * status. The module
returns a valid response.	

### **Related Commands:**

Section 2.1 %AANNTTCCFF, Section 2.25 ~AAI

## **Related Topics:**

Section A.1 INIT\* Pin Operation

### Notes:

It is recommended that the soft INIT timeout value is reset to 0 once any changes to the Baud Rate and checksum settings have been completed.

# 2.28 @AAGxTtt

### **Description:**

Reads the Steinhart coefficient of a user-defined type.

## Syntax:

#### @AAGxTtt[CHKSUM](CR)

Delimiter character
Address of the module to be read (00 to FF)
Command to read the Steinhart coefficient
A: reads Steinhart coefficient A
B: reads Steinhart coefficient B
C: reads Steinhart coefficient C
tt represents the type code of the user-defined
type to read the Steinhart coefficient.

### **Response:**

Valid con	mand: <b>!AA(Data)[CHKSUM](CR)</b>
Invalid c	mmand: <b>?AA[CHKSUM](CR)</b>
!	Delimiter character for a valid command
?	Delimiter character for an invalid command or
	invalid type code
AA	Address of the responding module (00 to FF)
(Data)	Eight hexadecimal digits to represent the
	Steinhart coefficient in IEEE-754 format. See
	Section 1.11 for details.

Command: @01GAT70 Response: !013A94030AReads the A coefficient of type 70 of module 01 and returns a value of 3A94030A, which is equivalent to  $1.129241x10^{-3}$ .

Command: @01GBT70 Response: !0139757ACFReads the B coefficient of type 70 of module 01 and returns a value of 39757ACF, which is equivalent to  $2.341077x10^{-4}$ .

Command: @01GCT70 Response: !0133BC73A5 Reads the C coefficient of type 70 of module 01 and returns a value of 33BC73A5, which is equivalent to 8.775468x10<sup>-8</sup>.

## **Related Commands:**

Section 2.29 @AARTTttR(data), Section 2.30 @AASxTttC(data)

## **Related Topics:**

Section 1.11 User-defined Types, Section A.6 Thermistor

# 2.29 @AARTTttR(Data)

## **Description:**

Reads the temperature associated with the input resistance of a user-defined type.

## Syntax:

### @AARTTttR(Data)[CHKSUM](CR)

- AA Address of the module to be read (00 to FF)
- RT Command to read the temperature associated with the input resistance of a user-defined type
- Ttt tt represents the type code of the user-defined type.
- R(Data) The (Data) consists of seven decimal digits, or five digits, decimal point and one additional digit, to represent the input resistance.

## **Response:**

Valid command:	<b>!AA(Data)[CHKSUM](CR)</b>
Invalid command:	?AA[CHKSUM](CR)
! Delimite	er character for a valid command
? Delimite	er character for an invalid command or
invalid t	ype code
AA Address	of the responding module (00 to FF)
(Data) The (Da	ta) consists of a +/- sign, three digits,
decimal	point and two additional digits to
represen	t the temperature associated with the
input res	sistance.

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

### **Examples:**

Command: @01RTT70R0104500 Response: !01-032.64 Reads the temperature associated with 104500 ohms of type 70 of module 01, and the module returns a value of -32.64 degree. Command: @01RTT70R00801.2 Response: !01+072.62 Reads the temperature associated with 801.2 ohms of type 70 of module 01, and the module returns a value

of 72.62 degree.

### **Related Commands:**

Section 2.22 ~AAD, Section 2.23 ~AADT, Section 2.28 @AAGxTtt, Section 2.30 @AASxTttC(data)

### **Related Topics:**

Section A.6 Thermistor

### Notes:

The temperature scale is set using the ~AADT command and can be read using the ~AAD command. See Sections 2.22 and 2.23 for details.

# 2.30 @AASxTttC(data)

## **Description:**

Sets the Steinhart coefficient of a user-defined type.

### Syntax:

### @AASxTttC(data)[CHKSUM](CR)

a	Delimiter character
AA	Address of the module to be set (00 to FF)
S	Command to set the Steinhart coefficient
X	A: sets Steinhart coefficient A
	B: sets Steinhart coefficient B
	C: sets Steinhart coefficient C
Ttt	tt represents the type code of the user-defined
	type to set the Steinhart coefficient.
C(Data)	The (Data) is eight hexadecimal digits in IEEE-
	754 format to represent the Steinhart coefficient.
	See Section 1.11 for details.

### **Response:**

Valid con	nmand: <b>!AA[CHKSUM](CR)</b>
Invalid c	ommand: <b>?AA[CHKSUM](CR)</b>
!	Delimiter character for a valid command
?	Delimiter character for an invalid command or
	invalid type code
AA	Address of the responding module (00 to FF)

Command: @01SAT70C3A94030A Response: !01 Sets the A coefficient of type 70 of module 01 to be 3A94030A, which is equivalent to 1.129241x10<sup>-3</sup>, and the module returns a valid response.

Command: @01SBT70C39757ACF Response: !01 Sets the B coefficient of type 70 of module 01 to be 39757ACF, which is equivalent to 2.341077x10<sup>-4</sup>, and the module returns a valid response.

Command: @01SCT70C33BC73A5 Response: !01 Sets the C coefficient of type 70 of module 01 to be 33BC73A5, which is equivalent to 8.775468x10<sup>-8</sup>, and the module returns a valid response.

## **Related Commands:**

Section 2.28 @AAGxTtt, Section 2.29 @AARTTttR(data)

## **Related Topics:**

Section 1.11 User-defined Types, Section A.6 Thermistor

## Notes:

If the resistance versus temperature data table of the thermistor is available, it is suggested that the @AARTTttR(data) command be used to verify the accuracy of the user-defined type.

# 2.31 @AACHCi

## **Description:**

Clears the high latched alarm of a channel.

### Syntax:

#### @AACHCi[CHKSUM](CR)

- ⓐ Delimiter character
- AA Address of the module to be set (00 to FF)
- CH Command to clear the high latched alarm
- Ci i represents which channel should have the high latched alarm cleared.

### Response:

- Valid command: **!AA(Data)[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**
- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel
- AA Address of the responding module (00 to FF)

Command: @01CHC2 Response: !01 Clears the high latched alarm of channel 2 of module 01, and the module returns a valid response.

### **Related Commands:**

Section 2.32 @AACLCi, Section 2.33 @AADHCi, Section 2.35 @AADLCi, Section 2.37 @AAHI(data)CiTOj, Section 2.38 @AALO(data)CiTOj

### **Related Topics:**

Section 1.12 Digital Outputs and Alarms

# 2.32 @AACLCi

### **Description:**

Clears the low latched alarm of a channel.

### Syntax:

#### @AACLCi[CHKSUM](CR)

- ⓐ Delimiter character
- AA Address of the module to be set (00 to FF)
- CL Command to clear the low latched alarm
- Ci i represents which channel should have the low latched alarm cleared.

### Response:

#### Valid command: **!AA(Data) [CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel
- AA Address of the responding module (00 to FF)

Command: @01CLC2 Response: !01 Clears the low latched alarm of channel 2 of module 01, and the module returns a valid response.

### **Related Commands:**

Section 2.31 @AACHCi, Section 2.33 @AADHCi, Section 2.35 @AADLCi, Section 2.37 @AAHI(data)CiTOj, Section 2.38 @AALO(data)CiTOj

### **Related Topics:**

Section 1.12 Digital Outputs and Alarms

# 2.33 @AADHCi

## **Description:**

Disables the high alarm of a channel.

### Syntax:

### @AADHCi[CHKSUM](CR)

- ⓐ Delimiter character
- AA Address of the module to be set (00 to FF)
- DH Command to disable the high alarm
- Ci i represents which channel should have the high alarm disabled.

### Response:

- Valid command: **!AA(Data)[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**
- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel
- AA Address of the responding module (00 to FF)

Command: @01DHC2 Response: !01 Disables the high alarm of channel 2 of module 01, and the module returns a valid response.

### **Related Commands:**

Section 2.31 @AACHCi, Section 2.32 @AACLCi, Section 2.35 @AADLCi, Section 2.37 @AAHI(data)CiTOj, Section 2.38 @AALO(data)CiTOj

### **Related Topics:**

Section 1.12 Digital Outputs and Alarms

# 2.34 @AADI

### **Description:**

Reads the status of the digital output ports.

## Syntax:

### @AADI[CHKSUM](CR)

(a)	Delimiter character
ĂA	Address of the module to be read (00 to FF)
DI	Command to read the digital output ports

### **Response:**

Valid cor	nmand: <b>!AAOO[CHKSUM](CR)</b>
Invalid co	ommand: <b>?AA[CHKSUM](CR)</b>
!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)
00	A two-digit hexadecimal value, where bit 0
	corresponds to DO0, bit 1 corresponds to DO1,
	etc. When the bit is 1, it denotes that the digital
	output port is on, and 0 denotes that the digital
	output port is off.

Command: @01DI Response: !0133 Reads the digital output port status of module 01 and returns 33h, which denotes that DO0, DO1, DO4 and DO5 are on and DO2 and DO3 are off.

## **Related Commands:**

Section 2.36 @AADODD

### **Related Topics:**

Section 1.12 Digital Outputs and Alarms

# 2.35 @AADLCi

### **Description:**

Disables the low alarm of a channel.

### Syntax:

#### @AADHCi[CHKSUM](CR)

- (a) Delimiter character
- AA Address of the module to be set (00 to FF)
- DL Command to disable the low alarm
- Ci i represents which channel should have the low alarm disabled.

### Response:

- Valid command: **!AA(Data)[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**
- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel
- AA Address of the responding module (00 to FF)

Command: @01DLC2 Response: !01 Disables the low alarm of channel 2 of module 01, and the module returns a valid response.

### **Related Commands:**

Section 2.31 @AACHCi, Section 2.32 @AACLCi, Section 2.33 @AADHCi, Section 2.37 @AAHI(data)CiTOj, Section 2.38 @AALO(data)CiTOj

### **Related Topics:**

Section 1.12 Digital Outputs and Alarms

## 2.36 @AADODD

## **Description:**

Sets the digital output ports.

### Syntax:

#### @AADODD[CHKSUM](CR)

- ⓐ Delimiter character
- AA Address of the module to be set (00 to FF)
- DO Command to set the digital output ports
- DD A two-digit hexadecimal value, where bit 0 corresponds to DO0, bit 1 corresponds to DO1, etc. When the bit is 1, it denotes that the digital output port is on, and 0 denotes that the digital output port is off.

### **Response:**

Valid cor	nmand: <b>!AA[CHKSUM](CR)</b>
Invalid co	mmand: <b>?AA[CHKSUM](CR)</b>
!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)

Command: @01DO33 Response: !01 Sets DO0 to on, DO1 to on, DO2 to off, DO3 to off, DO4 to on, and DO5 to on, and the module returns a valid response.

## **Related Commands:**

Section 2.34 @AADI

## **Related Topics:**

Section 1.12 Digital Outputs and Alarms

## Notes:

- **1.** If the digital output port is already set to be an alarm output port, then the value written to the port is ignored.
- **2.** When a host watchdog timeout occurs, the module will respond with an invalid command for this command and the DO value that was sent is ignored.

# 2.37 @AAHI(data)CiTOj

## **Description:**

Sets the high alarm of a channel.

### Syntax:

#### @AAHI(data)CiTOj[CHKSUM](CR)

0	(and) err ell'erre errel(erre)
(a)	Delimiter character
AA	Address of the module to be set (00 to FF)
HI	Command to set the high alarm
(data)	High alarm limit, which consists of a sign, three
	digits, a decimal point and two additional digits.
Ci	i represents which channel is to be checked for
	the high alarm.
Т	Alarm type:
	M: momentary alarm
	L: latched alarm
Oj	j specifies the digital output port to be used for
-	the alarm output.

## **Response:**

#### Valid command: **!AA[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel
- AA Address of the responding module (00 to FF)

Command: @01HI+090.00C0MO1 Response: !01
Sets the high alarm of channel 0 of module 01. The alarm limit is 90.0 degree. The alarm type is momentary. The alarm output port is DO1.
Command: @01HI+110.00C3LO5 Response: !01
Sets the high alarm of channel 3 of module 01. The alarm limit is 110.0 degree. The alarm type is latched. The alarm output port is DO5.

### **Related Commands:**

Section 2.22 ~AAD, Section 2.23 ~AADT, Section 2.31 @AACHCi, Section 2.32 @AACLCi, Section 2.33 @AADHCi, Section 2.38 @AALO(data)CiTOj

## **Related Topics:**

Section 1.12 Digital Outputs and Alarms

## Notes:

- The temperature scale of the temperature limit is set using the ~AADT command and can be read using the ~AAD command. See Sections 2.22 and 2.23 for details. If the temperature scale is changed, then the temperature limit should be changed accordingly. The default temperature scale is Celsius.
- 2. It is possible to have more than one alarm associated with a digital output port. The digital output port is turned on when one of the alarms is activated, and is turned off when all of the alarms associated are not activated.

# 2.38 @AALO(data)CiTOj

## **Description:**

Sets the low alarm of a channel.

#### Syntax:

#### @AALO(data)CiTOj[CHKSUM](CR)

00	
(a)	Delimiter character
AA	Address of the module to be set (00 to FF)
LO	Command to set the low alarm
(data)	Low alarm limit, which consists of a sign, three
	digits, a decimal point and two additional digits.
Ci	i represents which channel is to be checked for
	the low alarm.
Т	Alarm type:
	M: momentary alarm
	L: latched alarm
Oj	j specifies the digital output port to be used for
-	the alarm output.

## Response:

#### Valid command: **!AA[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel
- AA Address of the responding module (00 to FF)

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## **Examples:**

Command: @01LO-005.00C0MO1 Response: !01
Sets the low alarm of channel 0 of module 01. The alarm limit is -5.0 degree. The alarm type is momentary. The alarm output port is DO1.
Command: @01LO+010.00C3LO5 Response: !01
Sets the low alarm of channel 3 of module 01. The alarm limit is 10.0 degree. The alarm type is latched. The alarm output port is DO5.

#### **Related Commands:**

Section 2.22 ~AAD, Section 2.23 ~AADT, Section 2.31 @AACHCi, Section 2.32 @AACLCi, Section 2.33 @AADHCi, Section 2.37 @AAHI(data)CiTOj

## **Related Topics:**

Section 1.12 Digital Outputs and Alarms

## Notes:

- 1. The temperature scale of the temperature limit is set using the ~AADT command and can be read uisng the ~AAD command. See Sections 2.22 and 2.23 for details. If the temperature scale is changed, then the temperature limit should be changed accordingly. The default temperature scale is Celsius.
- 2. It is possible to have more than one alarm associated with a digital output port. The digital output port is turned on when one of the alarms is activated, and is turned off when all of the alarms associated are not activated.

# 2.39 @AARAOj

#### **Description:**

Reads the currently activated alarms associated with a digital output port.

## Syntax:

#### @AARAOj[CHKSUM](CR)

- ⓐ Delimiter character
- AA Address of the module to be read (00 to FF)
- RA Command to read the currently activated alarms associated with a digital output port.
- Oj j specifies the digital output port.

#### **Response:**

- Valid command: **!AAHHLL[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**
- Delimiter character for a valid command
   Delimiter character for an invalid command or invalid port
- AA Address of the responding module (00 to FF)
- HH A two-digit hexadecimal value to represent the currently activated high alarms associated with the digital output port, where bit 0 corresponds to channel 0, bit 1 corresponds to channel 1, etc. When the bit is 1, it denotes that there is an activated high alarm associated with the channel. When the bit is 0, it denotes that there are no activated high alarms associated with the channel.

LL A two-digit hexadecimal value to represent the currently activated low alarms associated with the digital output port, where bit 0 corresponds to channel 0, bit 1 corresponds to channel 1, etc. When the bit is 1, it denotes that there is an activated low alarm associated with the channel. When the bit is 0, it denotes that there are no activated low alarms associated with the channel.

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: @01RAO1 Response: !011122 Reads the currently activated alarms associated with the DO1 of module 01. The module responds with 1122, which denotes that there is an activated high alarm associated with channels 0 and 4, and an activated low alarm associated with channels 1 and 5.

## **Related Commands:**

Section 2.42 @AAROOj

## **Related Topics:**

Section 1.12 Digital Outputs and Alarms

# 2.40 @AARHCi

### **Description:**

Reads the high alarm settings of a channel.

### Syntax:

#### @AARHCi[CHKSUM](CR)

- ⓐ Delimiter character
- AA Address of the module to be read (00 to FF)
- RH Command to read the high alarm settings.
- Ci i represents from which channel the high alarm settings should be read.

#### **Response:**

#### Valid command: **!AA(Data)SOj[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel

AA Address of the responding module (00 to FF)

- (data) High alarm limit, which consists of a (+/-) sign, three digits, a decimal point and two additional digits.
- S Alarm type:
  - 0: alarm disabled
  - 1: momentary alarm
  - 2: latched alarm
- Oj j specifies the digital output port to be used for the alarm output.

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

### **Examples:**

Command: @01RHC0 Response: !01+090.00MO1 Reads the high alarm settings of channel 0 of module 01. The module responds that the high alarm limit is 90.0 degree, the alarm type is momentary and the alarm output port is DO1.

Command: @01RHC3 Response: !01+110.00LO5 Reads the high alarm settings of channel 3 of module 01. The module responds that the high alarm limit is 110.0 degree, the alarm type is latched and the alarm output port is DO5.

## **Related Commands:**

Section 2.31 @AACHCi, Section 2.32 @AACLCi, Section 2.33 @AADHCi, Section 2.37 @AAHI(data)CiTOj, Section 2.41 @AARLCi

#### **Related Topics:**

Section 1.12 Digital Outputs and Alarms

#### Notes:

The temperature scale of the temperature limit can be read using the ~AAD command. The default temperature scale is Celsius. See Section 2.22 for details.

# 2.41 @AARLCi

### **Description:**

Reads the low alarm setting of a channel.

#### Syntax:

#### @AARLCi[CHKSUM](CR)

- ⓐ Delimiter character
- AA Address of the module to be read (00 to FF)
- RL Command to read the low alarm setting.
- Ci i represents from which channel the low alarm setting should be read.

#### **Response:**

#### Valid command: **!AA(Data)SOj[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid channel

AA Address of the responding module (00 to FF)

- (data) Low alarm limit which consists of a (+/-) sign, three digits, a decimal point and two additional digits.
- S Alarm type:
  - 0: alarm disabled
  - 1: momentary alarm
  - 2: latched alarm
- Oj j specifies the digital output port to be used for the alarm output.

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

#### **Examples:**

Command: @01RLC0 Response: !01+010.00MO1 Reads the low alarm setting of channel 0 of module 01. The module responds that the low alarm limit is 10.0 degree, the alarm type is momentary and the alarm output port is DO1.

Command: @01RLC3 Response: !01-020.00LO5 Reads the low alarm setting of channel 3 of module 01. The module responds that the low alarm limit is -20.0 degree, the alarm type is latched and the alarm output port is DO5.

#### **Related Commands:**

Section 2.31 @AACHCi, Section 2.32 @AACLCi, Section 2.33 @AADHCi, Section 2.38 @AALO(data)CiTOj, Section 2.40 @AARHCi

#### **Related Topics:**

Section 1.12 Digital Outputs and Alarms

#### Notes:

The temperature scale of the temperature limit can be read using the ~AAD command. The default temperature scale is Celsius. See Section 2.22 for details.

# 2.42 @AAROOj

#### **Description:**

Reads the alarms associated with a digital output port.

### Syntax:

#### @AARAOj[CHKSUM](CR)

- ⓐ Delimiter character
- AA Address of the module to be read (00 to FF)
- RO Command to read the alarms associated with a digital output port.
- Oj j specifies the digital output port.

## **Response:**

- Valid command: **!AAHHLL[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**
- ! Delimiter character for a valid command
- ? Delimiter character for an invalid command or invalid port
- AA Address of the responding module (00 to FF)
- HH A two-digit hexadecimal value to represent the high alarms associated with the digital output port, where bit 0 corresponds to channel 0, bit 1 corresponds to channel 1, etc. When the bit is 1, it denotes that the high alarm of the channel is set. When the bit is 0, it denotes that the high alarm of the channel is disabled.

LL A two-digit hexadecimal value to represent the low alarms associated with the digital output port, where bit 0 corresponds to channel 0, bit 1 corresponds to channel 1, etc. When the bit is 1, it denotes that the low alarm of the channel is set. When the bit is 0, it denotes that the low alarm of the channel is disabled.

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## **Examples:**

Command: @01ROO1 Response: !011122 Reads the alarms associated with the DO1 of module 01. The module responds with 1122 meaning that the high alarms on channels 0 and 4 and the low alarms on channels 1 and 5 are associated with the DO1.

## **Related Commands:**

Section 2.39 @AARAOj

## **Related Topics:**

Section 1.12 Digital Outputs and Alarms

# 2.43 ~\*\*

## **Description:**

Informs all modules that the host is OK.

## Syntax:

~**[CHKSUM](CR)		
$\sim$	Delimiter character	
**	Host OK command	

## **Response:**

No response.

## **Examples:**

Command: ~\*\* No response Sends a "Host OK" command to all modules.

## **Related Commands:**

Section 2.44 ~AA0, Section 2.45 ~AA1, Section 2.46 ~AA2, Section 2.47 ~AA3EVV, Section 2.48 ~AA4, Section 2.49 ~AA5PPSS

## **Related Topics:**

Section A.2 Dual Watchdog Operation

# 2.44 ~AA0

#### **Description:**

Reads the host watchdog status of a module.

#### Syntax:

## ~AA0[CHKSUM](CR)

$\sim$	Delimiter character
AA	Address of the module to be read (00 to FF)
0	Command to read the module status

#### **Response:**

Valid con	nmand: <b>!AASS[CHKSUM](CR)</b>	
Invalid c	ommand: <b>?AA[CHKSUM](CR)</b>	
!	Delimiter character for a valid command	
?	Delimiter character for an invalid command	
AA	Address of the responding module (00 to FF)	
SS	Two hexadecimal digits that represent the host	
	watchdog status, where:	
	Bit 7: 0 indicates that the host watchdog is	
	disabled, and 1 indicates that the host watchdog	
	is enabled,	
	Bit 2: 1 indicates that a host watchdog timeout	
	has occurred, and 0 indicates that no host	
	watchdog timeout has occurred.	
	The host watchdog status is stored in EEPROM	
	and can only be reset by using the ~AA1	
	command.	

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

### **Examples:**

Command: ~010 Response: !0100 Reads the host watchdog status of module 01 and returns 00, meaning that the host watchdog is disabled and no host watchdog timeout has occurred. Command: ~020 Response: !0204 Reads the host watchdog status of module 02 and returns 04, meaning that a host watchdog timeout has occurred.

#### **Related Commands:**

Section 2.43 ~\*\*, Section 2.45 ~AA1, Section 2.46 ~AA2, Sec 2.47 ~AA3EVV, Section 2.48 ~AA4, Section 2.49 ~AA5PPSS

#### **Related Topics:**

Section A.2 Dual Watchdog Operation

# 2.45 ~AA1

#### **Description:**

Resets the host watchdog timeout status of a module.

#### Syntax:

#### ~AA1[CHKSUM](CR)

$\sim$	Delimiter character
AA	Address of the module to be reset (00 to FF)
1	Command to reset the host watchdog timeout
	status

#### **Response:**

Valid cor	nmand: <b>!AA[CHKSUM](CR)</b>
Invalid co	ommand: <b>?AA[CHKSUM](CR</b> )
!	Delimiter character for a valid command
?	Delimiter character for an invalid command
AA	Address of the responding module (00 to FF)

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: ~010 Response: !0104 Reads the host watchdog status of module 01 and shows that a host watchdog timeout has occurred. Command: ~011 Response: !01 Resets the host watchdog timeout status of module 01 and returns a valid response. Command: ~010 Response: !0100 Reads the host watchdog status of module 01 and

shows that no host watchdog timeout has occurred.

#### **Related Commands:**

Section 2.43 ~\*\*, Section 2.44 ~AA0, Section 2.46~AA2, Section 2.47~AA3EVV, Section 2.48 ~AA4, Section 2.49 ~AA5PPSS

#### **Related Topics:**

Section A.2 Dual Watchdog Operation

# 2.46 ~AA2

#### **Description:**

Reads the host watchdog timeout value of a module.

### Syntax:

#### ~AA2[CHKSUM](CR)

$\sim$	Delimiter character
AA	Address of the module to be read (00 to FF)

2 Command to read the host watchdog timeout value

### **Response:**

### Valid command : **!AAEVV[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

! Delimiter character for a valid command	!	Delimiter	character for	a valid com	nand
---	---	-----------	---------------	-------------	------

- ? Delimiter character for an invalid command
- AA Address of the responding module (00 to FF)
- E 1: the host watchdog is enabled 0: the host watchdog is disabled
- VV Two hexadecimal digits to represent the timeout value in tenths of a second, for example, 01 denotes 0.1 seconds and FF denotes 25.5 seconds.

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: ~012 Response: !011FF Reads the host watchdog timeout value of module 01 and returns FF, which denotes that the host watchdog is enabled and the host watchdog timeout value is 25.5 seconds.

#### **Related Commands:**

Section 2.43 ~\*\*, Section 2.44 ~AA0, Section 2.45 ~AA1, Section 2.47 ~AA3EVV, Section 2.48 ~AA4, Section 2.49 ~AA5PPSS

### **Related Topics:**

Section A.2 Dual Watchdog Operation

# 2.47 ~AA3EVV

#### **Description:**

Enables/disables the host watchdog and sets the host watchdog timeout value of a module.

## Syntax:

### ~AA3EVV[CHKSUM](CR)

$\sim$	Delimiter character
AA	Address of the module to be set (00 to FF)
3	Command to set the host watchdog
Е	1: enable the host watchdog
	0: disable the host watchdog
VV	Two hexadecimal digits to represent the timeout
	value in tenths of a second, for example, 01
	denotes 0.1 seconds and FF denotes 25.5
	seconds.

#### **Response:**

Valid cor	nmand:	!AA[CHKSUM](CR)
Invalid co	ommand:	?AA[CHKSUM](CR)
!	Delimiter	character for a valid command
?	Delimiter	character for an invalid command
AA	Address of	of the responding module (00 to FF)

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: ~013164 Response: !01 Enables the host watchdog of module 01 and sets the host watchdog timeout value to 10.0 seconds. The module returns a valid response. Command: ~012 Response: !01164 Reads the host watchdog timeout value of module 01. The module returns 164, which denotes that the host watchdog is enabled and the host watchdog timeout value is 10.0 seconds.

## **Related Commands:**

Section 2.43 ~\*\*, Section 2.44 ~AA0, Section 2.45 ~AA1, Section 2.46 ~AA2, Section 2.48 ~AA4, Section 2.49 ~AA5PPSS

## **Related Topics:**

Section A.2 Dual Watchdog Operation

#### Notes:

When a host watchdog timeout occurs, the host watchdog is disabled. The  $\sim$ AA3EVV command should be sent again to reenable the host watchdog.

# 2.48 ~AA4

#### **Description:**

Reads the power-on DO and safe DO values of a module.

## Syntax:

### ~AA4[CHKSUM](CR)

$\sim$	Delimite	er chara	cter	
		0.1	1 1	

- AA Address of the module to be read (00 to FF)
- 4 Command to read the power-on DO and safe DO values

## **Response:**

# Valid command : **!AAPPSS[CHKSUM](CR)** Invalid command: **?AA[CHKSUM](CR)**

!	Delimiter	character fo	or a valid	command	
---	-----------	--------------	------------	---------	--

- ? Delimiter character for an invalid command
- AA Address of the responding module (00 to FF)
- PP Two hexadecimal digits to represent the poweron DO value.
- SS Two hexadecimal digits to represent the safe DO value.

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

## Examples:

Command: ~014 Response: !010000 Reads the power-on DO value and the safe DO value of module 01 and returns 0000.

#### **Related Commands:**

Section 2.49 ~AA5PPSS

### **Related Topics:**

Section 1.12 Digital Outputs and Alarms, Section A.2 Dual Watchdog Operation

#### Notes:

Both the power-on value and the safe value have no effect on the DO ports that are associated with alarm outputs.

# 2.49 ~AA5PPSS

#### **Description:**

Sets the power-on DO and safe DO values of a module.

### Syntax:

#### ~AA5PPSS[CHKSUM](CR)

Delimiter character
Address of the module to be set (00 to FF)
Command to set the power-on and safe DO
values
Two hexadecimal digits to represent the power-
on DO value.
Two hexadecimal digits to represent the safe DO
value.

#### **Response:**

Valid com	and: <b>!AA[CHKSUM](CR)</b>	
Invalid con	mand: <b>?AA[CHKSUM](CR)</b>	
! [	elimiter character for a valid command	
? [	elimiter character for an invalid command	
AA A	ddress of the responding module (00 to FF)	

There will be no response if the command syntax is incorrect, there is a communication error, or there is no module with the specified address.

### Examples:

Command: ~0150000 Response: !01 Sets the power-on DO value to 0 and the safe DO value to 0. The module returns a valid response. Command: ~014 Response: !010000 Reads the power-on DO value and the safe DO value of module 01. The module returns 0000, which denotes that both the power-on DO value and the safe DO value are 0.

#### **Related Commands:**

Section 2.48 ~AA4

### **Related Topics:**

Section 1.12 Digital Output and Alarm, Section A.2 Dual Watchdog Operation

#### Notes:

Both the power-on value and the safe value have no effect on the DO ports that are associated with alarm outputs.

# 3. Modbus RTU Protocol

The Modbus protocol is developed by Modicon Inc., originally developed for Modicon controllers. Detailed information can be found at <u>http://www.modicon.com/techpubs/toc7.html</u>. You can also visit <u>http://www.modbus.org</u> to find more valuable information.

M-7000 series modules support the Modbus RTU protocol. The communication Baud Rates range from 1200bps to 115200bps. The parity, data bits and stop bits are fixed as no parity, 8 data bits and 1 stop bit. The following Modbus functions are supported by the M-7005.

<b>Function Code</b>	Description	Section
01 (0x01)	Read digital output status	3.1
02 (0x02)	Read input status	3.2
04 (0x04)	Read input channels	3.3
05 (0x05)	Write single digital output	3.4
15 (0x0F)	Write multiple digital outputs	3.5
70 (0x46)	Read/write module settings	3.6

If the function specified in the message is not supported, then the module responds as follows.

#### **Error Response**

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	Function code   0x80
02	Exception code	1 Byte	01

If a CRC mismatch occurs, the module will not respond.

# 3.1 01 (0x01) Read Digital Output Status

This function code is used to read the digital output channel status of a module.

#### Request

<b>_</b>			
00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x01
02~03	Starting channel	2 Bytes	0x00 to 0x05, where 0x00
			corresponds to channel 0, 0x01
			corresponds to channel 1, etc
04 ~ 05	Number of digital	2 Bytes	N, 1 to 6; (Starting channel + N)
	output channels		should be less than or equal to
	-		0x06

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x01
02	Byte count	1 Byte	1
03	Data of digital output channels	1 Byte	A bit corresponds to a channel. When the bit is 1 it denotes that the channel is ON. If the bit is 0 it denotes that the channel is OFF.

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x81
02	Exception code	~	02: starting channel out of range 03: (starting channel + number of digital output channels) out of range, incorrect number of bytes received

# 3.2 02 (0x02) Read Input Status

This function code is used to read the thermistor wire opening status of a module.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x02
02 ~ 03	Starting channel	2 Bytes	0x80 to 0x87, where 0x80
	_	-	corresponds to channel 0, 0x81
			corresponds to channel 1, etc
04 ~ 05	Number of input	2 Bytes	N, 1 to 7; (Starting channel $+$ N)
	channels	-	should be less than or equal to
			0x88

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x02
02	Byte count	1 Byte	1
03	Data of input	1 Byte	A bit corresponds to a channel.
	channels		When the bit is 1 it denotes that
			the channel is enabled and is either
			over-range, under-range or wire
			opening. If the bit is 0 it denotes
			that the channel is disabled or
			normal.

	<b>A</b>		
00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x82
02	Exception code	1 Byte	02: starting channel out of range 03: (starting channel + number of input channels) out of range, incorrect number of bytes received

# 3.3 04 (0x04) Read Input Channels

This function code is used to read from contiguous analog input channels.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x04
02 ~ 03	Starting channel	2 Bytes	0 to 7
$04 \sim 05$	Number of input	2 Bytes	1 to 8; (Starting channel $+$ N) $\leq$ =
	channels (N)	-	8.

#### Response

P				
00	Address	1 Byte	1 to 247	
01	Function code	1 Byte	0x04	
02	Byte count	1 Byte	2 x N	
03 ~	Data of input	2 x N	Data in 2's complement hex	
	channels	Bytes	format.	

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x84
02	Exception code	1 Byte	02: starting channel out of range 03: (starting channel + number of input channels) out of range, incorrect number of bytes received

# 3.4 05 (0x05) Write Single Digital Output

This function code is used to write to one digital output channel.

Request
---------

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x05
02 ~ 03	Channel	2 Bytes	0 to 5
04 ~ 05	Data	2 Bytes	FF00h for ON and 0000h for OFF.

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x04
$02 \sim 03$	Channel	2 Bytes	0 to 5
04 ~ 05	Data	2 Bytes	FF00h for ON and 0000h for OFF.

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x85
02	Exception code	1 Byte	02: channel out of range

# 3.5 15 (0x0F) Write Multiple Digital Output Channels

This function code is used to write to multiple digital output channels.

#### Request

	•		
00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x0F
02 ~ 03	Starting channel	2 Bytes	0 to 5
$04 \sim 05$	Number of	2 Bytes	1 to 6; (Starting channel $+$ N) $\leq$ =
	channels (N)		6.
06	Byte count	1 Byte	1
07 ~	Data of digital	1 Byte	A bit corresponds to a channel.
	output channels		When the bit is 1 it denotes that
			the channel is ON. If the bit is 0 it
			denotes that the channel is OFF.

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x0F
02 ~ 03	Starting channel	2 Bytes	0 to 5
04 ~ 05	Number of	2 Bytes	1 to 6
	channels (N)		

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x8F
02	Exception code	1 Byte	02: starting channel out of range 03: (starting channel + number of channels) out of range, incorrect number of bytes received

# 3.6 70 (0x46) Read/Write Module Settings

This function code is used to read the settings of the module or change the settings of the module. The following sub-function codes are supported.

<b>Sub-function Code</b>	Description	Section
00 (0x00)	Read the module name	3.6.1
04 (0x04)	Set the module address	3.6.2
05 (0x05)	Read the communication settings	3.6.3
06 (0x06)	Set the communication settings	3.6.4
07 (0x07)	Read the type code	3.6.5
08 (0x08)	Set the type code	3.6.6
32 (0x20)	Read the firmware version	3.6.7
37 (0x25)	Read the channel enable/disable status	3.6.8
38 (0x26)	Set the channel enable/disable	3.6.9
41 (0x29)	Read the miscellaneous settings	3.6.10
42 (0x2A)	Write the miscellaneous settings	3.6.11

If the module does not support the sub-function code specified in the message, then it responds as follows.

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	02: invalid sub-function code

## 3.6.1 Sub-function 00 (0x00) Read module name

This sub-function code is used to read the name of a module.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x00

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x00
03 ~ 06	Module name	4 Bytes	0x00 0x70 0x05 0x00 for M-7005

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: incorrect number of bytes received

## 3.6.2 Sub-function 04 (0x04) Set module address

This sub-function code is used to set the address of a module.

Request				
00	Address	1 Byte	1 to 247	
01	Function code	1 Byte	0x46	
02	Sub function code	1 Byte	0x04	
03	New address	1 Byte	1 to 247	
04 ~ 06	Reserved	3 Bytes	0x00 0x00 0x00	

#### Response

<b>L</b>			
00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
	Sub function code	1 Byte	0x04
03	Set address result		0: OK,
			others: error
04 ~ 06	Reserved	3 Bytes	0x00 0x00 0x00

#### **Error Response**

140

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: new address out of range, reserved bytes should be filled with zero, incorrect number of bytes received

# 3.6.3 Sub-function 05 (0x05) Read communication settings

This sub-function code is used to read the communication protocol settings of a module.

#### **Request**

00	Address	1 Byte	1 to 247		
01	Function code	1 Byte	0x46		
02	Sub function code	1 Byte	0x05		
03	Reserved	1 Byte	0x00		

#### Response

Respon			
00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x05
03	Reserved	1 Byte	0x00
04	Baud Rate	1 Byte	Baud Rate code, see Section 1.11
			for details.
$05 \sim 07$	Reserved	3 Bytes	0x00 0x00 0x00
08	Mode	1 Byte	0: DCON protocol
			1: Modubs RTU protocol
09 ~ 10	Reserved	2 Bytes	0x00 0x00

**Note**: This information is the data saved in the EEPROM and will be used for the next power-on reset. It is not the currently used settings.

00	Address	1 Byte	1 to 247		
01	Function code	1 Byte	0xC6		
02	Exception code	1 Byte	03: reserved byte should be filled with zero, incorrect number of bytes received		

#### **M-7005**

# 3.6.4 Sub-function 06 (0x06) Set communication settings

This sub-function code is used to set the communication protocol of a module.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x06
03	Reserved	1 Byte	0x00
04	Baud Rate	1 Byte	Baud Rate code, see Section 1.11
			for details.
05 ~ 07	Reserved	3 Bytes	0x00 0x00 0x00
08	Mode	1 Byte	0: DCON protocol
		-	1: Modubs RTU protocol
09 ~ 10	Reserved	2 Bytes	0x00 0x00

#### Response

00	Address	1 Byte	1 to 247
	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x06
03	Reserved	1 Byte	0x00
04	Baud Rate	1 Byte	0: OK, others: error
$05 \sim 07$	Reserved	3 Bytes	0x00 0x00 0x00
08	Mode	1 Byte	0: OK, others: error
09 ~ 10	Reserved	2 Bytes	0x00 0x00

**Note**: The new Baud Rate and protocol will be effective after the next power-on reset.

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: Baud Rate or mode out of range, reserved bytes should be filled with zero, incorrect number of bytes received

## 3.6.5 Sub-function 07 (0x07) Read type code

This sub-function code is used to read the type code information of a module.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x07
03	Reserved	1 Bytes	0x00
04	Channel	1 Byte	$0x00 \sim 0x07$ for M-7005

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x07
03	Type code	1 Byte	Type code, see Section 1.10 for
			details.

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: reserved bytes should be filled with zero, channel out of range, incorrect number of bytes received

## 3.6.6 Sub-function 08 (0x08) Set type code

This sub-function code is used to set the type code of a module.

Request					
00	Address	1 Byte	1 to 247		
01	Function code	1 Byte	0x46		
02	Sub function code	1 Byte	0x08		
03	Reserved	1 Byte	0x00		
04	Channel	1 Byte	$0x00 \sim 0x07$ for M-7005		
05	Type code	1 Byte	Type code, see Section 1.10 for		
			details.		

#### Response

00	Address	1 Byte	1 to 247		
01	Function code	1 Byte	0x46		
02	Sub function code	1 Byte	0x08		
03	Type code	1 Byte	0: OK		
			others: error		

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: type code out of range, channel out of range, reserved bytes should be filled with zero, incorrect number of bytes received

# 3.6.7 Sub-function 32 (0x20) Read firmware version

This sub-function code is used to read the firmware version information of a module.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x20

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x20
03	Major version	1 Byte	$0x00 \sim 0xFF$
04	Minor version	1 Byte	$0x00 \sim 0xFF$
05	Build version	1 Byte	$0x00 \sim 0xFF$

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: incorrect number of bytes received

# 3.6.8 Sub-function 37 (0x25) Read channel enabled/disabled status

This sub-function code is used to read the enabled/disabled status of each channel in a module.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x25

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x25
03	Enabled/disabled status	1 Byte	$0x00 \sim 0xFF$ , enabled/disabled status of each channel, where bit 0 corresponds to channel 0, bit 1 corresponds to channel 1, etc. When the bit is 1 it denotes that the channel is enabled and 0 denotes that the channel is disabled.

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: incorrect number of bytes
			received

# 3.6.9 Sub-function 38 (0x26) Set channel enable/disable

This sub-function code is used to specify the channels to be enabled in a module.

#### Request

1			
00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x26
03	Enable/disable	1 Byte	$0x00 \sim 0xFF$ , enable/disable
	setting		setting of each channel, where bit
	e		0 corresponds to channel 0, bit 1
			corresponds to channel 1, etc.
			When the bit is 1 it denotes that
			the channel is enabled and 0
			denotes that the channel is
			disabled.

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x26
03	Enable/disable	1 Byte	0: OK
	setting		others: error.

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: enable/disable setting out of range, incorrect number of bytes received

# 3.6.10 Sub-function 41 (0x29) Read miscellaneous settings

This sub-function code is used to read the miscellaneous settings of a module.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x29

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x29
03	Miscellaneous settings	1 Byte	0, not used for M-7005

Note: The reserved fields are filled with zeros.

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: incorrect number of bytes
			received

## 3.6.11 Sub-function 42 (0x2A) Write miscellaneous settings

This sub-function code is used to set the miscellaneous settings of a module.

#### Request

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x2A
03	Miscellaneous settings	1 Byte	0, not used for M-7005

Note: The reserved fields are filled with zeros.

#### Response

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0x46
02	Sub function code	1 Byte	0x2A
03	Miscellaneous	1 Byte	0: OK
	settings		others: error

00	Address	1 Byte	1 to 247
01	Function code	1 Byte	0xC6
02	Exception code	1 Byte	03: reserved bits should be filled with zero, incorrect number of
			bytes received

## 4. Troubleshooting

If you are having difficulty using the I-7000 series module, here are some suggestions that may help. If you cannot find the answers you need in these guides, contact ICP DAS Product Support. Contact information is located in Section 1.15.

### 4.1 Communicating with the module

If you attempt to communicate with the module and receive no response, first check the following:

- Ensure that the supplied power is within the range of +10 to +30 V DC. If the supplied power is OK, then the power LED should be on.
- When the module receives a command, the power LED is set to "off". The power LED is shown as "on" after the module responds. This method can be used to check whether the module has received a command sent from the host.
- If possible, use another device to check whether the host can communicate with the device through the same RS-485 network.
- If the host is a PC installed with a Windows operating system, then execute the DCON Utility to determine whether the module can be found. The DCON Utility can be downloaded from the ICP DAS website <u>http://www.icpdas.com</u>. The DCON Utility documentation can be found in the "Getting Started For I-7000 Series Modules" manual.
- Set the module to "INIT mode" and communicate with the module using the following settings: address 00, Baud Rate 9600bps and no checksum. See Section A.1 for details.

### 4.2 Reading Data

If the data read from the input channel is not correct, first check the following:

- Ensure that the type code and data format settings are correct. For the I-7005, the type code is set by using the \$AA7CiRrr command, see Section 2.12 for details. The data format is set by using the %AANNTTCCFF command.
- Connect a resistor, instead of thermistor sensor, using the thermistor connection as shown in Section 1.6. The resistance of the resistor should be less than 180000 ohms. Change the data format to ohms, see Sections 1.10 and 2.1, and check whether the data reading is correct.
- If the resistance read by the module is still incorrect, then it may be because the calibration parameters stored in the non-volatile memory are corrupted, which means that the module should be recalibrated. Be sure to read Section 1.9 in detail before performing the calibration. For the I-7005 and M-7005, you can send the \$AAS1 command, see Section 2.21 for details, to reload the factory calibration parameters.

## A. Appendix

### A.1 INIT Mode

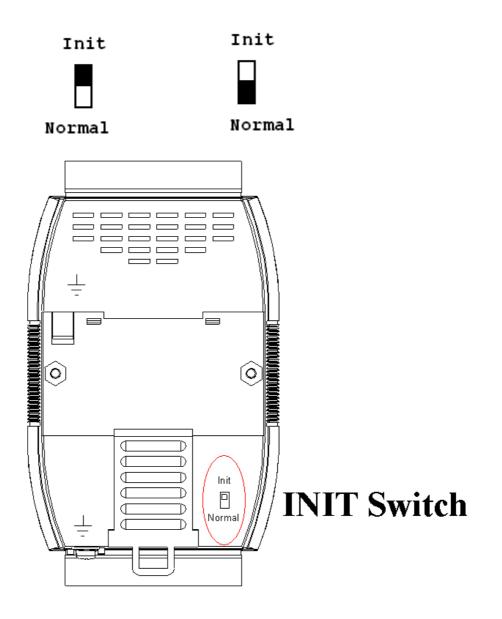
Each I-7000 module has a built-in EEPROM to store configuration information such as module address, type code, Baud Rate, etc. Occasionally, the configuration of a module may be forgotten and there are no visual indications of the configuration of the module. It is difficult to communicate with the module when the configuration of the module is unknown. To help avoid this problem, the I-7000 series has a special mode called **"INIT mode"**. When the module is powered on in **"INIT mode"** the configuration of the module is reset as follows, allowing it to be operated as normal.

- 1. Address: 00
- 2. Baud Rate: 9600 bps
- 3. No checksum

The configuration information stored in the EEPROM is not changed and can be read by sending the \$002(CR) command at 9600bps.

The %AANNTTCCFF command requires that the module is in INIT mode when changing the Baud Rate and checksum settings. See Section 2.1 for details.

In older modules, the INIT mode is accessed by connecting the INIT\* terminal to the GND terminal. The new I-7000 series modules have the INIT switch located on the rear side of the module to allow easier access to the INIT mode. For these modules, INIT mode is accessed by sliding the INIT switch to the Init position as shown below.



### A.2 Dual Watchdog Operation

#### **Dual Watchdog = Module Watchdog + Host Watchdog**

The Module Watchdog is a hardware reset circuit that monitors the operating status of the module. While working in harsh or noisy environments, the module may be shut down by external signals. The circuit allows the module to work continuously without disruption.

The Host Watchdog is a software function that monitors the operating status of the host. Its purpose is to prevent problems due to network/communication errors or host malfunctions. When a host watchdog timeout occurs, the module will reset all outputs to a safe state in order to prevent any erroneous operations of the controlled target.

I-7000 series modules include an internal Dual Watchdog, making the control system more reliable and stable.

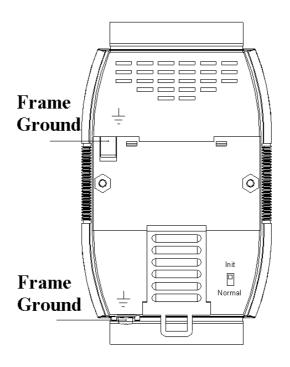
For more information regarding the Dual Watchdog, please refer to Chapter 5 of the "**Getting Started For I-7000 Series Modules**" manual that can be downloaded from the ICP DAS website <u>http://www.icpdas.com</u>.

### A.3 Frame Ground

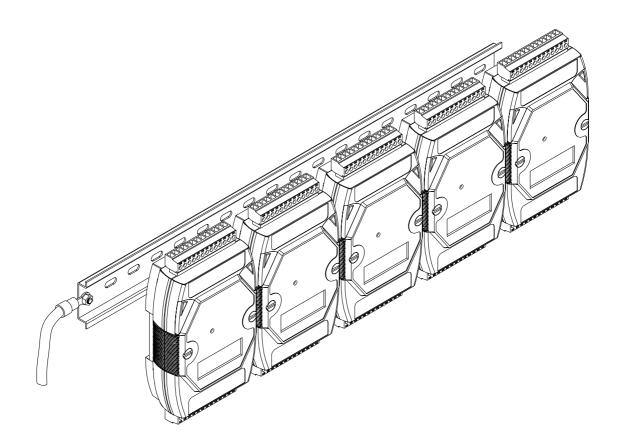
Electronic circuits are constantly vulnerable to Electro-Static Discharge (ESD), which become worse in a continental climate area. Some I-7000 modules feature a new design for the frame ground, which provides a path for bypassing ESD, allowing enhanced static protection (ESD) capability and ensures that the module is more reliable.

Either of the following options will provide a better protection for the module:

- 1. If the module is DIN rail mounted, connect the DIN rail to the earth ground because the DIN rail is in contact with the upper frame ground as shown in the figure below.
- 2. Alternatively, connect the lower frame ground terminal to a wire and connect the wire to the earth ground, as shown in the figure below.

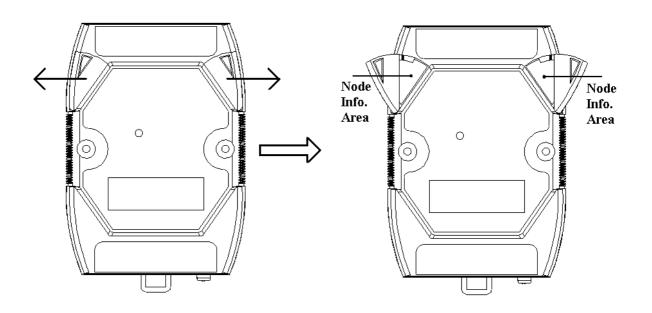


New DIN rail models are available that can easily be connected to the earth ground. Each is made of stainless steel, which is stronger than those made of aluminum. There is a screw at one end and a ring terminal is included as shown in the figure below. Refer to Section 1.14.1 for more information about the new DIN rail models.



### A.4 Node Information Area

Each I-7000 module has a built-in EEPROM to store configuration information such as module address, type code, Baud Rate, etc. One minor drawback is that there are no visual indications of the configuration of the module. New I-7000 modules include node information areas that are protected by a cover, as shown below, and can be used to make a written record of the node information, such as module address, Baud Rate, etc. To access the node information areas, first slide the covers outward, as shown in the figure below.



### A.5 Thermistor

A thermistor is a temperature sensitive resistor that can be used in temperature measurement, control and compensation circuitry. For most thermistors, the resistance decreases as the temperature rises and the relationship can be expressed as:

$$1/T = A + B \ln R_T + C (\ln R_T)^3$$

where  $R_T$  is the resistance in ohms at the temperature T in Kelvins (K = °C + 273.15). This is called the Steinhart-Hart equation.

Thermistors typically work over a relatively small temperature range of -60°C to 300°C. They are less stable than RTDs. However, they exhibit a large change in resistance proportional to a small change in temperature than RTDs and a much higher nominal resistance. They are less sensitive to lead resistance noise effects and can be transmitted over a large distance. No compensation for ambient temperature is needed. They are one of the most accurate types of temperature sensors.

### A.6 Resistance Measurement

The I-7005 and M-7005 modules can be used for resistance measurement. To measure the resistance, connect the resistor using thermistor connection, as shown in Section 1.6, and set the data format to ohms. To set the data format, send the %AANNTTCCFF command to the module, see Section 2.1 for details, or use the DCON utility, refer to Chapter 2 of the "Getting Started For I-7000 Series Modules" manual that can be downloaded from the ICP DAS website <u>http://www.icpdas.com</u>.

The maximum resistance that can be measured by I-7005 and M-7005 is 180000 ohms.